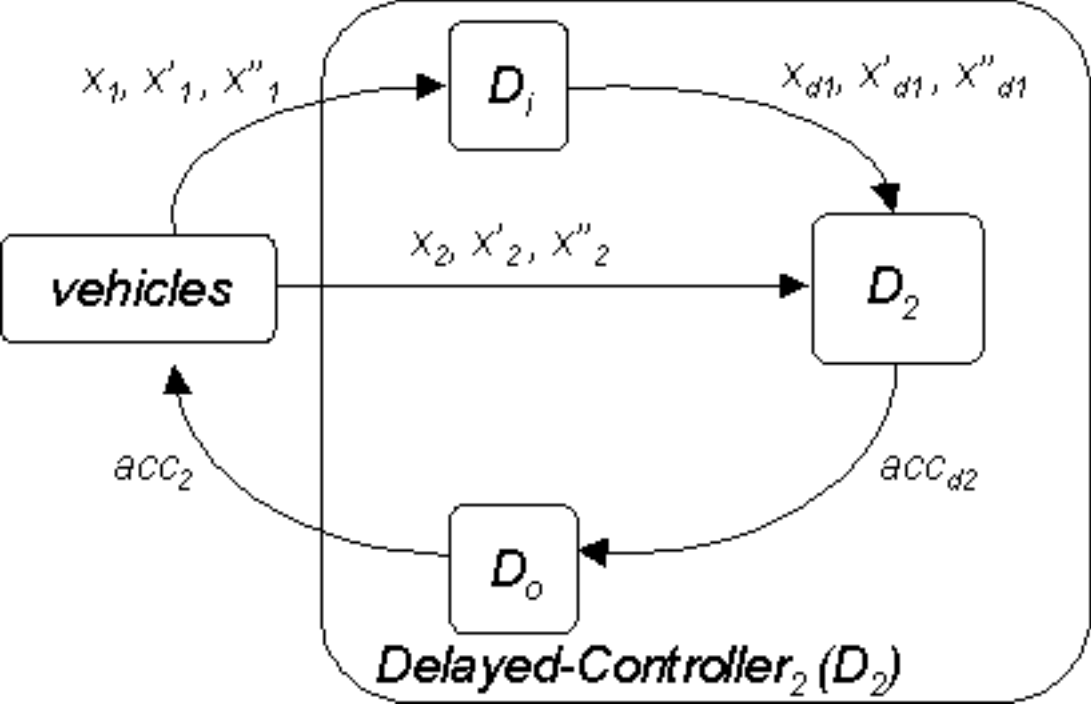
$x_1, x'_1, x''_1$
$D_i$
$x_{d1}, x'_{d1}, x''_{d1}$
vehicles
$x_2, x'_2, x''_2$
$D_2$
$acc_2$
$acc_{d2}$
$D_o$
Delayed-Controller$_2$ ($D_2$)