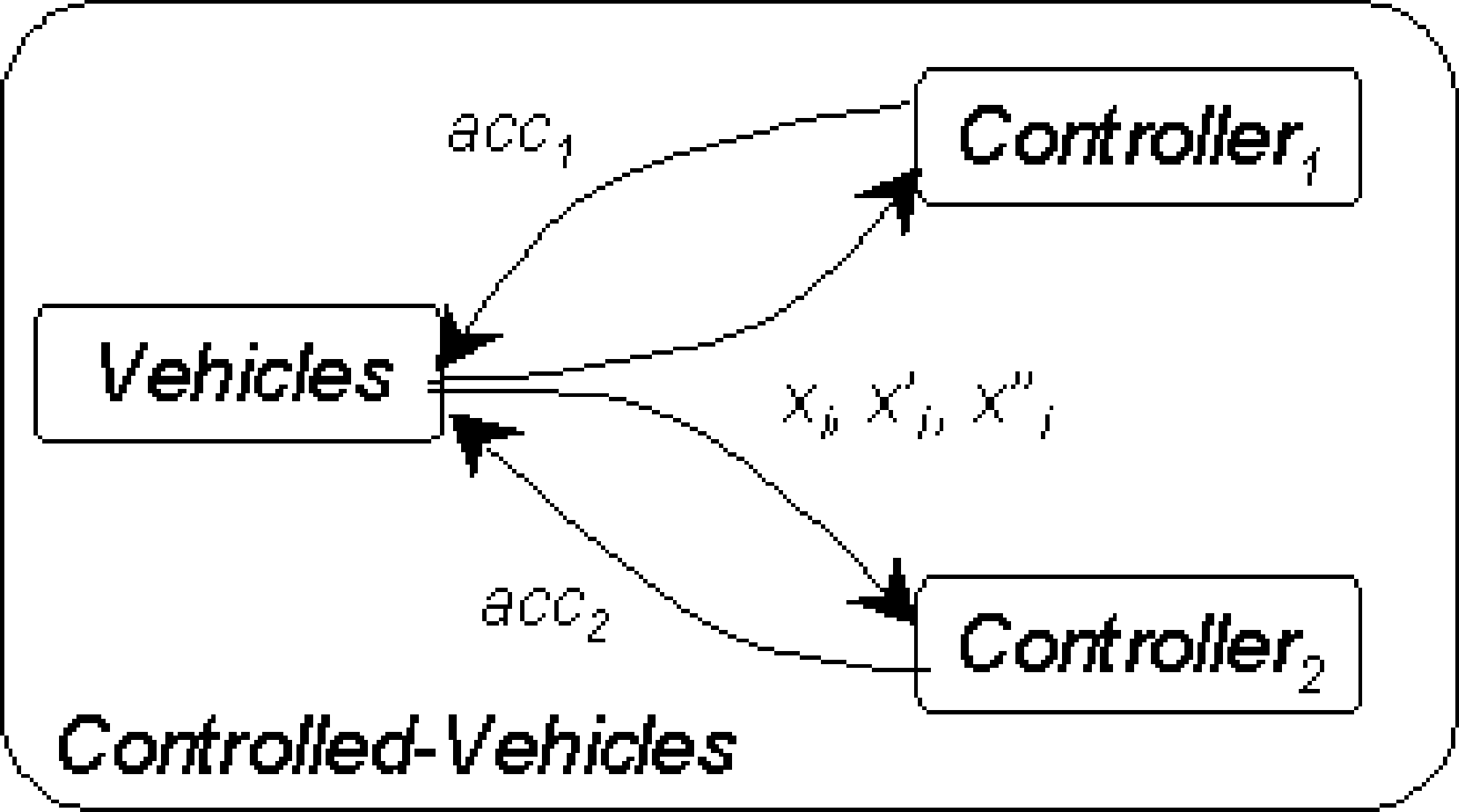
acc_1
Controller$_1$
Vehicles
x_i, x'_i, x''_i
acc_2
Controller$_2$
Controlled-Vehicles