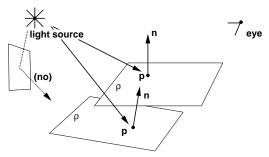
Lecture 5: Thursday, 23 September 1999

Today: Illumination Models Local (FvDfhp §14.1.1)

Also called *lighting*, *shading* models



One or more "point" light sources No occlusion (other than back-face determination) primary light sources only (no reflection)



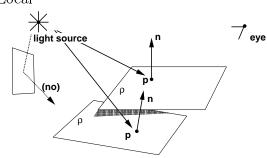
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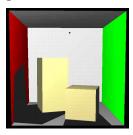
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Types of Illumination Models

Semi-Local



Shadow-tests for blocked *primary* sources Point light sources yield *hard* shadows No *secondary* light sources



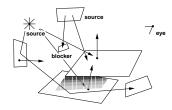
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Types of Illumination Models

Global (Ray-Tracing, Radiosity, Radiance)

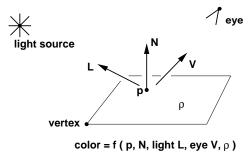


point, area, even volumetric light sources handles *soft* shadows (penumbrae) secondary, tertiary, etc., light sources comprehensive treatment of occlusion view-independent (diffuse) effects view-dependent (specular) effects



Local Illumination Models

Given point \mathbf{p} , normal \mathbf{N} , light \mathbf{L} , viewer \mathbf{V} Shade \mathbf{p} according to reflectance properties ρ



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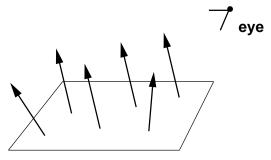
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Emissive Objects

Simplest illumination model possible (hack)



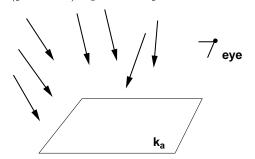
Every object emits light of some color, intensity

 I_e is the surface's emissive intensity I is the reflected intensity at shaded point Examples:

Phosphorescent, bioluminescent materials

Ambient Illumination

Ambient (perfused) light often present due to reflection



 $\label{eq:Quantitatively} \mbox{Quantitatively} \; (\mbox{I} = \mbox{Intensity}; \; \mbox{radiometric units later}) :$

 k_a is the ambient reflection coefficient I_a is the ambient light intensity

Examples:

Cloudy day

Building interior in daytime with no lights on

Hmm... Doesn't appearance change with

viewing direction?

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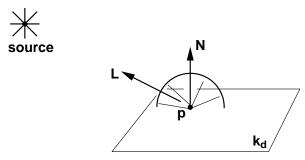
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Ideal Diffuse Reflection: Qualitative

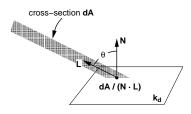


Ideal diffuse reflection occurs from perfect matte surfaces (not found in nature) reflection depends on angle between surface normal and direction to light source geometry causes viewer dependence to cancel out

Surface looks equally bright from all directions

Ideal Diffuse Reflection: Quantitative

Geometry of diffuse reflection:

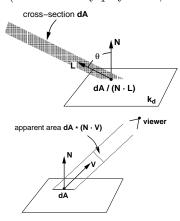


Beam with axis -L, area dA impinges on surface element with normal N
Beam distributes energy over an area $dA / \cos \theta$ Energy per unit area varies as $\mathbf{N} \cdot \mathbf{L}$

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Lambert's Law

Lambert's law (17th century physicist, mathematician)



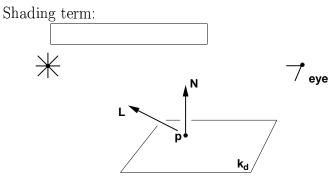
Diffuse reflected intensity $\propto \mathbf{N} \cdot \mathbf{V}$ But: apparent area $\propto 1/(\mathbf{N} \cdot \mathbf{V})$

Thus energy reflected toward viewer is

 $\propto \mathbf{N} \cdot \mathbf{L}, \, \mathbf{N} \cdot \mathbf{V}, \, 1/(\mathbf{N} \cdot \mathbf{V})$

Brightness is

Ideal Diffuse Reflection



 I_l is intensity of point light source k_d is coefficient of diffuse reflection $0 \le k_d < 1$ max prevents reflection from backfacing elements (underlying solid body opaque, thus "self-occluding") $\mathbf L$ effectively constant for distant light sources

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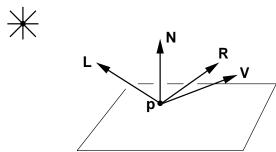
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Ideal Specular Reflection

Occurs from ideal (perfect) mirror Light along ${\bf L}$ bounces only in reflected direction ${\bf R}$



Quantitatively:

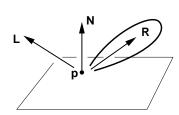
where $\delta(\mathbf{A}, \mathbf{B}) \equiv 1$ iff $\mathbf{A} = \mathbf{B}$, 0 otherwise

Uninteresting for most applications (non-physical)

Generalized Specular Reflection: Qualitative

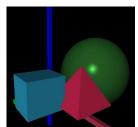
Occurs from "mirror-like" surfaces $\,$





Highlights occur whose sharpness varies with surface shininess

Highlight color only weakly dependent on surface color Reflection falls off around peak reflection direction ${\bf R}$



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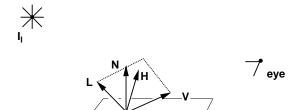
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Specular Reflection: Quantitative



Usually written in terms of surface normal, half-vector

 $\mathbf{H} = half-vector(\mathbf{V} + \mathbf{L})/|\mathbf{V} + \mathbf{L}|$

N = surface normal

V = direction to viewer

 $\mathbf{L} = \text{direction to light source}$

 $k_s = \text{coefficient of specular reflection}$

n = "shininess" parameter (sometimes e or s):

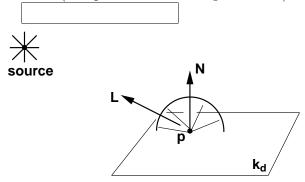
n = 1 yields smooth, broad highlight

 $n = \infty$ yields

n typically ranges from 1 to a few hundred

Phong Illumination Model (CACM 18(6), June 1975)

Diffuse term (independent of viewing direction)



I = reflected intensity

 $k_d = \text{coefficient of diffuse reflection}$

N = surface normal

L = direction to light source

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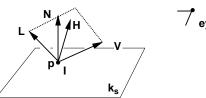
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Phong Illumination

Specular term (dependent on viewing direction)





 $\mathbf{H} = half\text{-}vector\left(\mathbf{V} + \mathbf{L}\right)/|\mathbf{V} + \mathbf{L}|$

N = surface normal

 $\mathbf{V} = \text{direction to viewer}$

L = direction to light source

 $k_s = \text{coefficient of specular reflection}$

n = "shininess" parameter

Computing the reflection vector R

 ${f R}$ is ${f L}$ mirrored about ${f N}$





Partition **L** into components \mathbf{L}_{\parallel} and \mathbf{L}_{\perp} ; negate \mathbf{L}_{\perp}

$$\begin{split} \mathbf{R} &= \mathbf{L}_{\parallel} - \mathbf{L}_{\perp} \\ &= \mathbf{L}_{\parallel} - (\mathbf{L} - \mathbf{N}(\mathbf{L} \cdot \mathbf{N})) \\ &= \mathbf{N}(\mathbf{L} \cdot \mathbf{N}) - \mathbf{L} + \mathbf{N}(\mathbf{L} \cdot \mathbf{N}) \\ &= \boxed{\label{eq:local_problem}} \end{split}$$

 \mathbf{L} (and therefore $\mathbf{N} \cdot \mathbf{L}$) are constant for distant sources (directional lights) But $-\mathbf{L}$ varies for local light sources!

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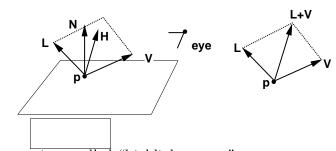
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Computing the half-vector H

 ${f H}$ is simply halfway between ${f L}$ and ${f V}$





 ${f H}$ sometimes called "highlight vector" hold ${f L}$, ${f V}$ fixed, vary ${f N}$ to find maximal highlight

Distance Attenuation

Model falloff of intensity with distance Problem: inverse quadratic falloff works poorly at long distances: varies too slowly at short distances: varies too quickly due to non-physicality of point light! In practice, can model attenuation with parameters c_k :

$$f_{att}(d_L) = \min\left(\frac{1}{c_1 + c_2 d_L + c_3 d_L^2}, 1\right)$$

 d_L is distance from surface element **to light** c_1 prevents blowup due to very close light sources c_2 models linear falloff due to large area light sources c_3 models quadratic falloff due to small, bright sources min prevents $f_{att}(d_L)$ from becoming greater than 1 Determining reasonable c_k problematic in practice

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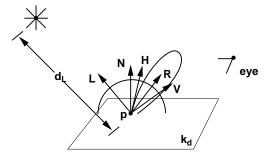
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Phong Illumination – Aggregate

Monochromatic lights and surfaces:

$$I = I_a k_a + f_{att}(d_L) I_l [k_d(\mathbf{N} \cdot \mathbf{L}) + k_s(\mathbf{N} \cdot \mathbf{H})^n]$$



Colored lights and surfaces:

$$I_{\lambda} = I_{a\lambda}k_aC_{d\lambda} + f_{att}(d_L)I_{l\lambda}[k_dC_{d\lambda}(\mathbf{N}\cdot\mathbf{L}) + k_s(\mathbf{N}\cdot\mathbf{H})^n]$$

Typically, one equation for each spectral component e.g., R ($\lambda = 620 \text{nm}$), G ($\lambda = 550 \text{nm}$), B ($\lambda = 440 \text{nm}$) Note: specular term independent of material properties

Approximation, with empirically derived parameters Caution: Phong model is not physically correct!

Spectral integration; fall off; energy conservation

When to Apply Lighting Equation?

Apply in object space

 $\operatorname{Adv}:$ easy to compute normals

Disady: Must transform lights to object space

So: apply in world coordinates

Adv: lights usually specified in world space

This is most common practice, but:

- 1) What about vertices outside frustum?
- 2) How are obj. space normals handled?

Some systems shade pixel fragments at end of pipe!

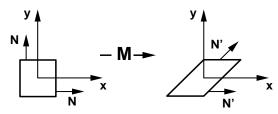
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Transforming Normal Vectors

Suppose we apply a transformation \mathbf{M} to an object What are the normals of the transformed object? Suppose we are shearing in x. Then

$$\mathbf{M} = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Look at normals (0,1) and (1,0) of a square:



If we apply \mathbf{M} , we get (1,1) and (1,0)!

Transforming Normal Vectors

Object vertices \mathbf{v} are transformed as $\mathbf{M}\mathbf{v}$ Consider vector \mathbf{v} , and \mathbf{n} such that $\mathbf{n} \perp \mathbf{v}$

$$\mathbf{n}^T \mathbf{v} = 0$$

(This is the implicit eq'n of something. What?) For any (non-singular) transformation matrix \mathbf{M}

$$\mathbf{n}^T \mathbf{M}^{-1} \mathbf{M} \mathbf{v} = 0$$

which can be rewritten as

$$(\mathbf{n}^T \mathbf{M}^{-1})(\mathbf{M} \mathbf{v}) = 0$$

thus the *transpose* of the transformed normal is

$$\mathbf{n}^T \mathbf{M}^{-1}$$

and the transformed normal itself is

$$(\mathbf{n}^T \mathbf{M}^{-1})^T = \mathbf{M}^{-T} \mathbf{n}$$

Normal \mathbf{n} , under action of \mathbf{M} , becomes $\mathbf{M}^{-T}\mathbf{n}$

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Example: Shear

For example above,

$$\mathbf{M} = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

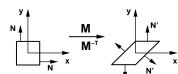
Its inverse M^{-1} is

$$\mathbf{M}^{-1} = \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Its inverse transpose $\mathbf{M}^{-\mathbf{T}}$ is

$$\mathbf{M}^{-\mathbf{T}} = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Now normals (0, 1) and (1, 0) map to:



(0,1) and (1,-1), respectively Note length change! How do we fix this?

Lighting: Simplifying Assumptions

Incorrect modeling of light source geometry

Can't get finite energy from zero volume!

Incorrect modeling of absorptive media (haze, etc.)

Bogus intensity attenuation with distance

No modeling of *scattering* due to air, etc.

Decreasing contrast, increasing blueness with distance No dependence on wavelength λ , thin film, etc.

No dependence on polarization

No dependence on azimuthal angle of incidence

No dependence on time

Things are not so simple in reality!

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