

# Lower Bounds for Restricted-Use Objects\*

## Extended Abstract

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### ABSTRACT

Concurrent objects play a key role in the design of applications for multi-core architectures, making it imperative to precisely understand their complexity requirements. For some objects, it is known that implementations can be significantly more efficient when their usage is restricted. However, apart from the specific restriction of one-shot implementations, where each process may apply only a single operation to the object, very little is known about the complexities of objects under general restrictions.

This paper draws a more complete picture by defining a large class of objects for which an operation applied to the object can be “perturbed”  $L$  consecutive times, and proving lower bounds on the time and space complexity of deterministic implementations of such objects. This class includes bounded-value max registers, limited-use approximate and exact counters, and limited-use collect and compare-and-swap objects;  $L$  depends on the number of times the object can be accessed or the maximum value it supports.

For implementations that use only historyless primitives, we prove lower bounds of  $\Omega(\min(\log L, n))$  on the worst-case step complexity of an operation, where  $n$  is the number of processes; we also prove lower bounds of  $\Omega(\min(L, n))$  on the

space complexity of these objects. When arbitrary primitives can be used, we prove that either some operation incurs  $\Omega(\min(\log L, n))$  memory stalls or some operation performs  $\Omega(\min(\log L, n))$  steps.

In addition to these deterministic lower bounds, the paper establishes a lower bound on the expected step complexity of restricted-use randomized approximate counting in a weak oblivious adversary model.

### Categories and Subject Descriptors

D.1.3 [Programming Techniques]: Concurrent Programming—*Distributed programming*; F.2.2 [Analysis of Algorithms and Problem Complexity]: Nonnumerical Algorithms and Problems

### General Terms

Theory, Algorithms

### Keywords

Concurrent objects, lower bounds, restricted-use objects, perturbable objects

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<sup>†</sup>Supported in part by the *Israel Science Foundation* (grant number 1227/10).

<sup>‡</sup>Supported by the Simons Postdoctoral Fellows Program

<sup>§</sup>Supported in part by the *Israel Science Foundation* (grant number 1227/10).

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SPAA'12, June 25–27, 2012, Pittsburgh, Pennsylvania, USA.  
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## 1. INTRODUCTION

With multi-core and multi-processor systems now prevalent, there is growing need to gain better understanding of concurrent objects and, specifically, to establish lower bounds on the cost of implementing them. An important general class of concurrent objects, defined by Jayanti, Tan and Toueg [15], are *perturbable* objects, including widely-used objects, such as *counters*, *max registers*, *compare-and-swap*, *single-writer snapshot* and *fetch-and-add*.

Lower bounds are known for *long-lived* implementations of perturbable objects, where processes apply an unbounded number of operations to the object. For example, Jayanti *et al.* [15] consider obstruction-free implementations of perturbable objects from *historyless* primitives, such as *read*, *write*, *test-and-set* and *swap*. They prove that such implementations require  $\Omega(n)$  space and that the worst-case step-complexity of the operations they support is  $\Omega(n)$ , where  $n$  is the number of processes sharing the object.

In some applications, however, objects are used in a restricted manner. For example, there might be a bound on the total number of operations applied on the object, or a bound on the values that the object needs to support. When an object is designed to allow only restricted use, it is sometimes possible to construct more efficient implementations than for the general case.

Indeed, Aspnes, Attiya and Censor-Hillel [3] showed that at least some restricted-use perturbable objects admit implementations that “beat” the lower bound of [15]. For example, a max register can do a write of  $v$  in  $O(\min(\log v, n))$  steps, while a counter limited to  $m$  increments can do each increment in  $O(\min(\log^2 m, n))$  steps. Such a restricted-use counter leads to a randomized consensus algorithm with  $O(n)$  individual step complexity [4], while restricted-use counters and max registers are used in a mutual exclusion algorithm with sub-logarithmic amortized work [7].

This raises the natural question of determining lower bounds on the complexity of restricted-use objects. The proof of Jayanti *et al.* [15] breaks for restricted-use objects because the executions constructed by this proof exceed the restrictions on these objects.

For the specific restriction of *one-time* object implementations, where each process applies exactly one operation to the object, there are lower bounds which are logarithmic in the number of processes, for specific objects [2, 1, 6] and generic perturbable objects [14]. Yet, these techniques yield bounds that are far from the upper bounds, e.g., when the object can be perturbed a super-polynomial number of times.

This paper draws a more complete picture of the cost of implementing restricted-use objects by studying the middle ground. We give time and space lower bounds for implementations of objects that are only required to work under restricted usage, for general families of restrictions.

We define the notion of *L-perturbable objects* that strictly generalizes classical perturbability; specific examples are bounded-value max registers, limited-use approximate and exact counters, and limited-use compare-and-swap and collect objects.<sup>1</sup>  $L$ , the perturbation bound, depends on the number of times the object can be accessed or the maximum value it can support (see Table 1).

For  $L$ -perturbable objects, we show lower bounds on the step and space complexity of obstruction-free deterministic implementations from historyless primitives. The step complexity lower bound is  $\Omega(\min(\log L, n))$ , and its proof uses a technique that we call *backtracking covering*, which is a quantified version of a technique introduced by Fich, Hendler and Shavit in [11] and later used in [5]. The space complexity lower bound is  $\Omega(\min(L, n))$ .

We also consider implementations that can apply *arbitrary* primitives not just historyless primitives, and use the *memory stalls* measure [8] to quantify the contention incurred by such implementations. We extend backtracking covering to prove that either an implementation’s worst-case operation step complexity is  $\Omega(\min(\log L, n))$  or some operation incurs  $\Omega(\min(\log L, n))$  stalls.

In addition to our deterministic lower bounds, we estab-

<sup>1</sup>A single-writer snapshot object is also a collect object (the converse is, in general, false). Therefore, our lower bounds for the collect object also hold for the single-writer snapshot object.

lish a lower bound of  $\Omega\left(\frac{\log \log m - \log \log c}{\log \log \log m}\right)$  on the expected step complexity of *randomized  $m$ -valued  $c$ -multiplicative-accurate counters*, a particularly weak class of counters that allow a multiplicative error of factor at most  $c$ . Our lower bound employs Yao’s Principle [16] and assumes a weak oblivious adversary. Table 1 summarizes the lower bounds for specific  $L$ -perturbable objects.

Aspnes *et al.* [3] prove lower bounds on obstruction-free implementations of max registers and approximate counters from historyless primitives: an  $\Omega(\min(\log m, n))$  step lower bound for deterministic implementations and a  $\Omega(\log m / \log \log m)$  lower bound, when  $m \leq n$ , on the expected step complexity of randomized implementations. These bounds, however, use a different proof technique, which is specifically tailored for the semantics of the particular objects, and does not seem to generalize to the restricted-use versions of *arbitrary* perturbable objects. Moreover, they neither prove space-complexity lower bounds nor consider implementations from arbitrary primitives.

## 2. MODEL AND DEFINITIONS

A shared-memory system consists of  $n$  *asynchronous* processes  $p_1, \dots, p_n$  communicating by applying primitive operations (*primitives*) on shared *base objects*. An application of each such primitive is a shared memory *event*. A *step* taken by a process consists of local computation followed by one shared memory event.

A primitive is *nontrivial* if it may change the value of the base object to which it is applied, e.g., a *write* or a *read-modify-write*, and *trivial* otherwise, e.g., a *read*. Let  $o$  be a base object that is accessed with two primitives  $f$  and  $f'$ ;  $f$  *overwrites*  $f'$  on  $o$  [10], if starting from any value  $v$  of  $o$ , applying  $f'$  and then  $f$  results in the same value as applying just  $f$ , using the same input parameters (if any) in both cases. A set of primitives is *historyless* if all the nontrivial primitives in the set overwrite each other; we also require that each such primitive overwrites itself. A set that includes the write and swap primitives is an example of a historyless set of primitives.

### 2.1 Executions and Operations

An *execution fragment* is a sequence of shared memory events applied by processes. An execution fragment is  $p_i$ -free if it contains no steps of process  $p_i$ . An *execution* is an execution fragment that starts from an initial configuration (in which all shared variables and processes’ local states assume their initial values). For execution fragments  $\alpha$  and  $\beta$ , we let  $\alpha\beta$  denote the execution fragment which results when the events of  $\beta$  are concatenated to those of  $\alpha$ .

An *operation instance* of an operation  $Op$  on an implemented object is a subsequence of an execution, in which some process  $p_i$  performs the operation  $Op$  on the object. The primitives applied by the operation instance may depend on the values of the shared base objects before this operation instance starts and during its execution ( $p_i$ ’s steps may be interleaved with steps of other processes).

An execution is *well-defined* if it may result when processes each perform a sequence of operation instances according to their algorithms. All the executions we consider are well-defined.

An implementation is *obstruction-free* [12] if a process ter-

	perturbation bound ( $L$ )	step complexity	max(steps, stalls)	space complexity	rand. step complexity
compare & swap	$\sqrt[3]{m} - 1$	$\Omega(\min(\log m, n))$	$\Omega(\min(\log m, n))$	$\Omega(\min(\sqrt[3]{m}, n))$	—
collect	$m - 1$	$\Omega(\min(\log m, n))$	$\Omega(\min(\log m, n))$	$\Omega(\min(m, n))$	—
max register	$m - 1$	$\Omega(\min(\log m, n))$ (also [3])	$\Omega(\min(\log m, n))$	$\Omega(\min(m, n))$	$\Omega(\frac{\log \log m}{\log \log \log m})$ (for $m \leq n$ , [3])
$k$ -additive counter	$\sqrt{\frac{m}{k}} - 1$	$\Omega(\min(\log m - \log k, n))$ (also [3])	$\Omega(\min(\log m - \log k, n))$	$\Omega(\min(\sqrt{\frac{m}{k}}, n))$	$\Omega(\frac{\log \log m}{\log \log \log m})$ (for $m \leq n$ )

**Table 1: Summary of lower bounds for restricted-use objects; where  $m$  is the maximum value assumed by the object or the bound on the number of operations applied to it. All the bounds are derived in this paper, except when stated otherwise.**

minates its operation instance if it runs in isolation long enough.

A process  $p$  is *active* after execution  $\alpha$  if  $p$  is in the middle of performing an operation instance, i.e.,  $p$  has applied at least one event of the operation instance in  $\alpha$ , but the instance is not complete in  $\alpha$ . Let  $active(\alpha)$  denote the set of processes that are active after  $\alpha$ . If  $p$  is not active after  $\alpha$ , we say that  $p$  is *idle* after  $\alpha$ .

A base object  $o$  is *covered after* an execution  $\alpha$  if there is a process  $p$  in the configuration resulting from  $\alpha$  that has a nontrivial event about to access  $o$ ; we say that  $p$  *covers*  $o$  after  $\alpha$ .

## 2.2 Restricted-Use Objects

Our main focus in this paper is on objects that support restricted usage. One example of such objects are objects that have a limit on the number of operation instances that can be performed on them, as captured by the following definition. An  $m$ -*limited-use* object is an object that allows at most  $m$  operation instances;  $m$  is the *limit* of the object.

Another type of objects with restricted usage are objects that have a value associated with their state which cannot exceed some bound. Examples are bounded max-registers and bounded counters [3], whose definitions we now provide.

A *max-register* is a linearizable [13] object that supports a **Write** ( $v$ ) operation, which writes the value  $v$  to the object, and a **ReadMax** operation, which returns the maximum value written by a **Write** operation instance linearized before it. In the bounded version of these objects, the object is only required to satisfy its specification if its associated value does not exceed a certain threshold.

A *counter* is a linearizable object that supports a **CounterIncrement** operation and a **CounterRead** operation, which returns the number of **CounterIncrement** operation instances linearized before it. In a  $k$ -*additive-accurate counter*, every **CounterRead** operation returns a value within  $\pm k$  of the number of **CounterIncrement** operation instances linearized before it. A  $c$ -*multiplicative-accurate counter* is a counter for which any **CounterRead** operation returns a value  $x$  with  $v/c \leq x \leq vc$ , where  $v$  is the number of **CounterIncrement** operation instances linearized before it.

A  $b$ -*bounded max register* takes values in  $\{0, \dots, b - 1\}$ . A  $b$ -*bounded counter* is a counter that takes values in  $\{0, \dots, b - 1\}$ .

For a  $b$ -bounded object  $\mathcal{O}$ ,  $b$  is the *bound* of  $\mathcal{O}$ .

We also consider collect and compare-and-swap objects.

A *collect* object provides two operations: a *store*( $val$ ) by process  $p_i$  sets  $val$  to the latest value for  $p_i$ . A *collect* operation  $cop$  returns a *view*,  $\langle v_1, \dots, v_n \rangle$ , satisfying the following

properties: 1) if  $v_j = \perp$ , then no *store* operation by  $p_j$  completes before  $cop$  starts, and 2) if  $v_j \neq \perp$ , then  $v_j$  is the operand of a *store* operation  $sop$  by  $p_j$  that starts before  $cop$  completes and there is no store operation by  $p_j$  that starts after  $sop$  completes and completes before  $cop$  starts.

A linearizable  $b$ -valued *compare-and-swap* object has a value in  $\{1, \dots, b\}$  and supports the operations *read* and *CAS*( $u, v$ ), for all  $u, v \in \{1, \dots, b\}$ . When the object's value is  $u$  (as determined by the sequence of operation instances on the object that were linearized), *CAS*( $u, v$ ) changes its value to  $v$  and returns *true*; when the object's value differs from  $u$ , *CAS*( $u, v$ ) returns *false* and does not change the object's value.

## 3. LOWER BOUNDS FOR DETERMINISTIC RESTRICTED-USE OBJECTS

In this section, we prove lower bounds for obstruction-free implementations of some restricted-use objects. Our starting point is the definition of *perturbable* objects by Jayanti *et al.* [15]. Roughly speaking, an object is perturbable if in some class of executions, events applied by an operation of one process influence the response of an operation of another process. The flavor of the argument used by Jayanti *et al.* to obtain their linear lower bound is that since the perturbed operation needs to return different responses with each perturbation, it must be able to distinguish between perturbed executions, implying that it must perform an increasing number of accesses to base objects.

The formal definition of perturbable objects is as follows.

**DEFINITION 1.** (See Figure 1.) *An object  $\mathcal{O}$  is perturbable if there is an operation instance  $op_n$  by process  $p_n$ , such that for every  $p_n$ -free execution  $\alpha\lambda$  where no process applies more than a single event in  $\lambda$  and for some process  $p_\ell \neq p_n$  that applies no event in  $\lambda$ , there is an extension of  $\alpha, \gamma$ , consisting of events by  $p_\ell$ , such that  $p_n$  returns different responses when performing  $op_n$  by itself after  $\alpha\lambda$  and after  $\alpha\gamma\lambda$ .*

We observe that  $\alpha\gamma\lambda$  in the above definition is a well-defined execution if  $\alpha\lambda$  is well-defined. This is because no process applies more than a single event in  $\lambda$  and  $p_\ell$  applies no events in  $\lambda$ , hence no process can distinguish between the two executions before it applies its last event.

The linear lower bounds [15] on the space and step complexity of obstruction-free implementations on perturbable objects (as defined in Definition 1 above) are obtained by constructing executions of unbounded length, hence they do not apply in general for restricted-use objects.

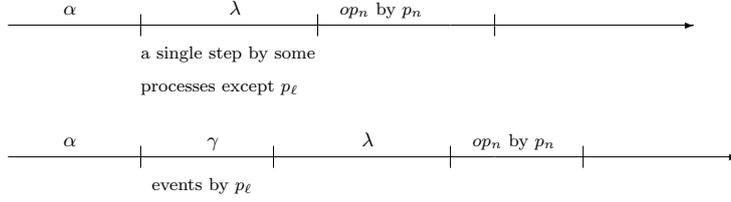


Figure 1: A perturbable object:  $op_n$  returns different responses in the two executions.

To prove lower bounds for restricted-use objects, we define a class of  $L$ -perturbable objects. As opposed to the definition of a perturbable object, we do not require every execution of an  $L$ -perturbable object to be perturbable, since this requirement is in general not satisfied by restricted-use objects. For such objects, some executions already reach the limit or bound of the object, not allowing any further operation to affect the object, which rules out a perturbation of these executions. To achieve our lower bounds we only need to show the existence of a special perturbing sequence of executions rather than attempting to perturb every execution. The longer the sequence, the higher the lower bound, since the perturbed operation will have to access more base objects in order to distinguish between executions in the sequence and be able to return different responses.

**DEFINITION 2.** An object  $O$  is  $L$ -perturbable if there exists an operation instance  $op_n$  by  $p_n$  such that an  $L$ -perturbing execution of  $O$  can be constructed as follows: The empty execution is 0-perturbing. Assume the object has a  $(k-1)$ -perturbing execution  $\alpha_{k-1}\lambda_{k-1}$ , where no process applies more than a single event in  $\lambda_{k-1}$ .

1. If  $|\lambda_{k-1}| = n - 1$ , then we say that  $\alpha_{k-1}\lambda_{k-1}$  is saturated, and the execution  $\alpha_k\lambda_k$  with  $\alpha_k = \alpha_{k-1}$ ,  $\lambda_k = \lambda_{k-1}$  is  $k$ -perturbing.
2. Otherwise, if there exists a process  $p_\ell \neq p_n$  that applies no event in  $\lambda_{k-1}$  and an extension of  $\alpha_{k-1}$ ,  $\gamma$ , consisting of events by  $p_\ell$ , such that  $p_n$  returns different responses when performing  $op_n$  by itself after  $\alpha_{k-1}\lambda_{k-1}$  and after  $\alpha_{k-1}\gamma\lambda_{k-1}$ , then we define a  $k$ -perturbing execution as follows. Let  $\gamma = \gamma'e\gamma''$ , where  $e$  is the first event of  $\gamma$  such that  $op_n$  returns different responses after  $\alpha_{k-1}\lambda_{k-1}$  and after  $\alpha_{k-1}\gamma'e\lambda_{k-1}$ . Let  $\lambda$  be a permutation of the events in  $\lambda_{k-1}$  and the event  $e$ , and let  $\lambda'$ ,  $\lambda''$  be any two sequences of events such that  $\lambda = \lambda'\lambda''$ . The execution  $\alpha_k\lambda_k$  is  $k$ -perturbing, where  $\alpha_k = \alpha_{k-1}\gamma'\lambda'$  and  $\lambda_k = \lambda''$ .

If an object is  $L$ -perturbable, then, starting from the initial configuration, we may construct a sequence of  $L + 1$  perturbing executions,  $\alpha_k\lambda_k$ , for  $0 \leq k \leq L$ , each of which extending its predecessor perturbing execution. If for some  $i$ ,  $\alpha_i\lambda_i$  is saturated, then we cannot further extend the sequence of perturbing executions since we do not have available processes to perform the perturbation. However, in this case we have lower bounds that are linear in  $n$ . For presentation simplicity, we assume in this case that the rest of the sequence's perturbing executions are identical to  $\alpha_i\lambda_i$ .

Definition 2 allows flexibility in determining which of the events of  $\lambda_{k-1}$  are contained in  $\lambda_k$  and which are contained in  $\alpha_k$ . We use this flexibility to prove lower bounds on the step, space and stall-complexity of  $L$ -perturbable objects.

The definition implies that every perturbable object is  $L$ -perturbable for every integer  $L \geq 0$ ; hence, the class of  $L$ -perturbable objects generalizes the class of perturbable objects. On the other hand, there are  $L$ -perturbable objects that are not perturbable; for example, a  $b$ -bounded  $n$ -process max register, for  $b \in \text{poly}(n)$ , is not perturbable in general, by the algorithm of [3]. That is, the class of perturbable objects is a proper subset of the class of  $L$ -perturbable objects.

The next lemma establishes that several common restricted-use objects are  $L$ -perturbable, where  $L$  is a function of the limit on the number of different operations that may be applied to them. The challenge in the proof is in increasing  $L$ , which later translates to higher lower bounds.

**LEMMA 1.** 1. An obstruction-free implementation of a  $b$ -bounded-value max register is  $(b-1)$ -perturbable.

2. An obstruction-free implementation of an  $m$ -limited-use max register is  $(m-1)$ -perturbable.

3. An obstruction-free implementation of an  $m$ -limited-use counter is  $(\sqrt{m}-1)$ -perturbable.

4. An obstruction-free implementation of a  $k$ -additive-accurate  $m$ -limited-use counter is  $(\sqrt{\frac{m}{k}}-1)$ -perturbable.

5. An obstruction-free implementation of an  $m$ -limited-use  $b$ -valued compare-and-swap object is  $(\sqrt[3]{m}-1)$ -perturbable (if  $b \geq n$ ).

6. An obstruction-free implementation of an  $m$ -limited-use collect object is  $(m-1)$ -perturbable.

**PROOF.** We present the proofs for representative objects; proofs for other objects appear in the full paper.

1. Let  $\mathcal{O}$  be a  $b$ -bounded-value max register and consider an obstruction-free implementation of  $\mathcal{O}$ . We show that  $\mathcal{O}$  is  $(b-1)$ -perturbable for a **ReadMax** operation instance  $op_n$  of  $p_n$ , by induction, where the base case for  $r = 0$  is immediate for all objects. We perturb the executions by writing values that increase by one to the max register. This guarantees that  $op_n$  has to return different values each time, while getting closer to the limit of the object as slowly as possible.

Formally, let  $r < b$  and let  $\alpha_{r-1}\lambda_{r-1}$  be an  $(r-1)$ -perturbing execution of  $\mathcal{O}$ . If  $\alpha_{r-1}\lambda_{r-1}$  is saturated, then, by case (1) of Definition 2, it is also an  $r$ -perturbing execution.

Otherwise, our induction hypothesis is that  $op_n$  returns  $r-1$  when run after  $\alpha_{r-1}\lambda_{r-1}$ . For the induction step, we build an  $r$ -perturbing execution after which the value returned by  $op_n$  is  $r$ . Since  $\alpha_{r-1}\lambda_{r-1}$  is not saturated, there is a process  $p_\ell \neq p_n$  that does not take steps in  $\lambda_{r-1}$ . Let  $\gamma$  be the execution fragment

by  $p_\ell$  where it first finishes any incomplete operation in  $\alpha$  and then performs a **Write** operation to the max register with the value  $r \leq b-1$ . Then  $op_n$  returns the value  $r$  when run after  $\alpha_{r-1}\gamma\lambda_{r-1}$ , and  $r-1$  when run after the  $(r-1)$ -perturbing execution  $\alpha_{r-1}\lambda_{r-1}$ . It follows that  $r$ -perturbing executions may be constructed from  $\alpha_{r-1}\lambda_{r-1}$  and  $\gamma$  as specified by Definition 2.

2. The proof for an  $m$ -limited-use max register appears in the full paper.
3. When  $\mathcal{O}$  is an  $m$ -limited-use counter, we use a proof similar to the one we used for a limited-use max register, where we perturb a **CounterRead** operation  $op_n$  by applying **CounterIncrement** operations. The subtlety in the case of a counter comes from the fact that a single perturbing operation may not be sufficient for guaranteeing that  $op_n$  returns a different value after  $\alpha_{r-1}\lambda_{r-1}$  and after  $\alpha_{r-1}\gamma\lambda_{r-1}$ , since we do not know how many of the **CounterIncrement** operations by processes that are active after  $\alpha_{r-1}$  were linearized. As there are at most  $r-1$  such operations, in order to ensure that different values are returned by  $p_n$  after these two executions, we construct  $\gamma$  by letting the process  $p_\ell$  apply  $r$  **CounterIncrement** operations after finishing any incomplete operation in  $\alpha_{r-1}$ . This can be done as long as  $r \leq \sqrt{m}$  in order not to pass the limit on the number of operations allowed, which will be  $1 + \sum_{r=1}^{\sqrt{m}} r = 1 + \frac{(\sqrt{m}-1)\sqrt{m}}{2} \leq m$ .
4. For a  $k$ -additive-accurate  $m$ -limited-use counter, the proof is similar to that of a counter, except that  $p_\ell$  needs to perform an even larger number of **CounterIncrement** operations in  $\gamma$ , because of the inaccuracy allowed in the returned value of the **CounterRead** operation  $op_n$ . The details appear in the full paper.
5. Let  $\mathcal{O}$  be an  $m$ -limited-use  $b$ -bounded *compare-and-swap* object,  $b \geq n$ . We show that it is  $(\sqrt[3]{m}-1)$ -perturbable for a *read* operation instance by  $p_n$ , by induction, where the base case for  $r=0$  is immediate for all objects. In our construction, all processes except for  $p_n$  perform only *CAS* operation instances.

Let  $r < \sqrt[3]{m}-1$  and let  $\alpha_{r-1}\lambda_{r-1}$  be an  $(r-1)$ -perturbing execution of  $\mathcal{O}$ . If  $\alpha_{r-1}\lambda_{r-1}$  is saturated, then, by case (1) of Definition 2, it is also an  $r$ -perturbing execution.

Otherwise, our induction hypothesis is that  $\alpha_{r-1}\lambda_{r-1}$  includes at most  $\sum_{i=1}^{r-1} i^2$  *CAS* operation instances. Let  $u$  be the value returned by  $op_n$  after  $\alpha_{r-1}\lambda_{r-1}$ , and let  $j$  denote the number of processes that apply events in  $\lambda_{r-1}$  and let  $p_{r-1}^1, \dots, p_{r-1}^j$  be these processes. Let  $\xi$  be an execution fragment that follows  $\alpha_{r-1}$  in which all active processes other than  $p_{r-1}^1, \dots, p_{r-1}^j$  finish any incomplete operation instances they started in  $\alpha_{r-1}$ . For  $k \in \{1, \dots, j\}$ , let  $(u_k, v_k)$  denote the operands of the last *CAS* operation instance started by  $p_{r-1}^k$  in  $\alpha_{r-1}$ . Since  $\alpha_{r-1}\lambda_{r-1}$  is not saturated and since  $r-1 < \sqrt[3]{m}-1$ , there is a process  $p_\ell \notin \{p_{r-1}^1, \dots, p_{r-1}^j\} \cup \{p_n\}$  and, moreover, there is a value  $v \in \{1, \dots, n\} \setminus \{u, u_1, \dots, u_j\}$ .

Denote by  $\beta$  the sequence of operation instances  $CAS(u, v)CAS(v_1, v) \dots CAS(v_j, v)$ , denote by  $\beta^r$  the

sequence of operation instances resulting from concatenating  $r$  copies of  $\beta$  and let  $\gamma = \xi\beta^r$ .

We claim that  $\mathcal{O}$ 's value after  $\alpha_{r-1}\gamma\lambda_{r-1}$  is  $v$ . Consider  $\mathcal{O}$ 's value after  $p_\ell$  executes  $\beta$  once after  $\alpha_{r-1}\xi$ . There are two possibilities: either  $\mathcal{O}$ 's value is  $v$  (in which case it remains  $v$  also after  $\alpha\gamma$ ), or, otherwise, all the *CAS* instances in  $\beta$  failed, implying that one or more of the operation instances performed by  $p_{r-1}^1, \dots, p_{r-1}^j$  are linearized when execution fragment  $\gamma$  is performed. In the latter case, consider  $\mathcal{O}$ 's value after  $p_\ell$  executes  $\beta$  twice after  $\alpha_{r-1}\xi$ . Once again, either  $\mathcal{O}$ 's value is  $v$  (and remains  $v$  also after  $\alpha_{r-1}\gamma$ ), or, otherwise, additional operation instances performed by  $p_{r-1}^1, \dots, p_{r-1}^j$  are linearized when the second instance of execution fragment  $\beta$  is performed. Applying this argument iteratively and noting that  $j \leq r-1$ , by construction, establishes our claim.

Consider the execution  $\alpha_{r-1}\gamma\lambda_{r-1}\phi$ , where  $\phi$  is an execution of *read* by  $p_n$ . Then  $\phi$  must return  $v$ , whereas an execution of *read* by  $p_n$  after  $\alpha_{r-1}\lambda_{r-1}$  returns  $u \neq v$ . Execution  $\alpha_r\lambda_r$  can now be constructed as in the proofs for limited use max registers and counters. The number of operation instances applied by  $p_\ell$  in  $\gamma$  is  $(j+1) \cdot r \leq r^2$ . Since  $\mathcal{O}$  allows only  $m$  operation instances, this implies that the sequence can have length  $\sqrt[3]{m}-1$ , because the total number of operation instances will be  $1 + \sum_{r=1}^{\sqrt[3]{m}-1} r^2 < m$ .

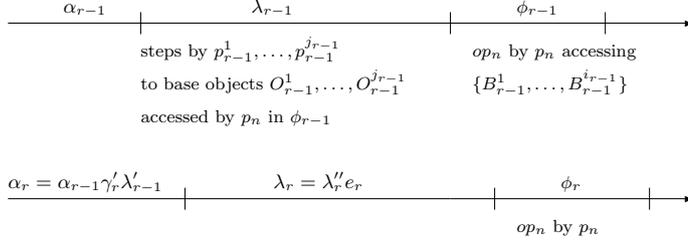
6. Let  $\mathcal{O}$  be an  $m$ -limited-use collect object and consider an obstruction-free implementation of  $\mathcal{O}$ . We show that  $\mathcal{O}$  is  $(m-1)$ -perturbable for a *collect* operation instance  $op_n$  of  $p_n$ , by induction, where the base case for  $r=0$  is immediate for all objects. We perturb the executions by having processes store values that change their collect component. This guarantees that  $op_n$  has to return different values each time, while getting closer to the limit of the object as slowly as possible.

Formally, let  $r < m$  and let  $\alpha_{r-1}\lambda_{r-1}$  be an  $(r-1)$ -perturbing execution of  $\mathcal{O}$ . If  $\alpha_{r-1}\lambda_{r-1}$  is saturated, then, by case (1) of Definition 2, it is also an  $r$ -perturbing execution.

Otherwise, Let  $V = \langle v_1, \dots, v_n \rangle$  denote the value that is returned by a *collect* operation by  $p_n$  after  $\alpha_{r-1}\lambda_{r-1}$ . Since  $\alpha_{r-1}\lambda_{r-1}$  is not saturated, there is a process  $p_\ell \neq p_n$  that does not take steps in  $\lambda_{r-1}$ . Let  $\gamma$  be the execution fragment by  $p_\ell$  where it first finishes any incomplete operation in  $\alpha$  and then applies an *update*( $v'_\ell$ ) operation to  $\mathcal{O}$ , for some  $v'_\ell \neq v_\ell$ . Then  $op_n$  must return different values when run after  $\alpha_{r-1}\gamma\lambda_{r-1}$  and after the  $(r-1)$ -perturbing execution  $\alpha_{r-1}\lambda_{r-1}$ . It follows that  $r$ -perturbing executions may be constructed from  $\alpha_{r-1}\lambda_{r-1}$  and  $\gamma$  as specified by Definition 2.  $\square$

### 3.1 Lower bounds for implementations using historyless objects

We define the concept of an access-perturbation sequence, and prove a step-complexity lower bound for objects that admit such a sequence.



**Figure 2: An access-perturbation sequence of length  $L$ : the above describes the executions for every  $r$ ,  $1 \leq r \leq L$ . Notice that  $\alpha_r \lambda_r$  is  $p_n$ -free for every  $r$ .**

DEFINITION 3. (See Figure 2.) An access-perturbation sequence of length  $L$  of an operation instance  $op_n$  by process  $p_n$  on an object  $\mathcal{O}$  is a sequence of executions  $\{\alpha_r \lambda_r \phi_r\}_{r=0}^L$ , such that  $\alpha_0 \lambda_0$  is empty,  $\phi_0$  is an execution of  $op_n$  by  $p_n$  starting from the initial configuration, and for every  $r$ ,  $1 \leq r \leq L$ , the following properties hold:

1. The execution  $\alpha_r \lambda_r$  is  $p_n$ -free.
2. In  $\phi_r$ , process  $p_n$  runs solo after  $\alpha_r \lambda_r$  until it completes the operation instance  $op_n$ , in the course of which it accesses the base objects  $B_r^1, \dots, B_r^{i_r}$ .
3.  $\lambda_r$  consists of  $j_r \geq 0$  nontrivial events applied by  $j_r$  distinct processes,  $p_r^1, \dots, p_r^{j_r}$  to distinct base objects  $O_r^1, \dots, O_r^{j_r}$ , respectively, all of which are accessed by  $p_n$  in  $\phi_r$ . If  $j_r = n - 1$ , we say that  $\alpha_r \lambda_r \phi_r$  is saturated.
4. (a) If  $\alpha_{r-1} \lambda_{r-1} \phi_{r-1}$  is saturated, then we let  $\alpha_r = \alpha_{r-1}$ ,  $\lambda_r = \lambda_{r-1}$  and  $\phi_r = \phi_{r-1}$ .  
(b) Otherwise, we let  $\alpha_r = \alpha_{r-1} \gamma'_r \lambda'_{r-1}$ , and  $\lambda_r = \lambda''_r e_r$ , where  $\lambda'_{r-1}$  is the subset of  $\lambda_{r-1}$  containing all events to base objects that are not accessed by  $p_n$  in  $\phi_r$ ,  $\lambda''_r$  is the subset of  $\lambda_{r-1}$  containing all events to base objects that are accessed by  $p_n$  in  $\phi_r$ , and  $\gamma'_r e_r$  is an execution fragment by a process  $p_{\ell_r}$  not taking steps in  $\lambda_{r-1}$ , where  $e_r$  is its first nontrivial event to a base object in  $\{B_{r-1}^1, \dots, B_{r-1}^{i_{r-1}}\} \setminus \{O_{r-1}^1, \dots, O_{r-1}^{j_{r-1}}\}$ .

We now prove that every  $L$ -perturbable objects has an access-perturbation sequence of length  $L$ .

LEMMA 2. An  $L$ -perturbable object implementation from historyless primitives has an access-perturbation sequence of length  $L$ .

PROOF. Let  $\mathcal{O}$  be an  $L$ -perturbable object implementation from historyless primitives. We show that it has an access-perturbation sequence of length  $L$ , for the operation  $op_n$  as defined in Definition 3. The proof is by induction, where we prove the existence of the execution  $\alpha_r \lambda_r \phi_r$ , for every  $r$ ,  $0 \leq r \leq L$ . To allow the proof to go through, in addition to proving that the execution  $\alpha_r \lambda_r \phi_r$  satisfies the four conditions of Definition 3, we will prove that  $\alpha_r \lambda_r$  is  $r$ -perturbing.

For the base case,  $r = 0$ ,  $\alpha_0 \lambda_0$  is empty and  $\phi_0$  is an execution of  $op_n$  starting from the initial configuration. Moreover, the empty execution is 0-perturbing. We next assume the construction of the sequence up to  $r - 1 < L$  and construct the next execution  $\alpha_r \lambda_r \phi_r$  as follows.

By the induction hypothesis, the execution  $\alpha_{r-1} \lambda_{r-1}$  is  $(r - 1)$ -perturbing. If  $\alpha_{r-1} \lambda_{r-1}$  is saturated, then, by case

(1) of Definition 2,  $\alpha_r = \alpha_{r-1}$ ,  $\lambda_r = \lambda_{r-1}$  and  $\alpha_r \lambda_r$  is  $r$ -perturbing. Moreover, by property 4(a) of Definition 3,  $\alpha_r \lambda_r \phi_r$  is the  $r$ 'th access-perturbation execution, where  $\phi_r = \phi_{r-1}$ .

Assume otherwise. Then, by property 2 of Definition 2, there is a process  $p_{\ell_r} \neq p_n$  that does not take steps in  $\lambda_{r-1}$ , for which there is an extension of  $\alpha_{r-1}$ ,  $\gamma_r$ , consisting of events by  $p_{\ell_r}$ , such that  $p_n$  returns different responses when performing  $op_n$  by itself after  $\alpha_{r-1} \lambda_{r-1}$  and after  $\alpha_{r-1} \gamma_r \lambda_{r-1}$ . As per Definition 2, let  $\gamma_r = \gamma'_r e_r \gamma''_r$ , where  $e_r$  is the first event of  $\gamma$  such that  $op_n$  returns different responses after  $\alpha_{r-1} \lambda_{r-1}$  and after  $\alpha_{r-1} \gamma'_r e_r \lambda_{r-1}$ . Clearly  $e_r$  is a nontrivial event.

Denote by  $\phi_r$  the execution of  $op_n$  by  $p_n$  after  $\alpha_{r-1} \gamma'_r e_r \lambda_{r-1}$ . Since  $op_n$  returns different values after  $\alpha_{r-1} \lambda_{r-1}$  and after  $\alpha_{r-1} \gamma'_r e_r \lambda_{r-1}$ , and since the implementation uses only historyless primitives, this implies that  $e_r$  is applied to some base object  $B$  not in  $\{O_{r-1}^1, \dots, O_{r-1}^{j_{r-1}}\}$  that is accessed by  $p_n$  in  $\phi_r$ .

We define  $\lambda'_{r-1}$  to be the subsequence of  $\lambda_{r-1}$  containing all events to base objects that are not accessed by  $p_n$  in  $\phi_r$ , and  $\lambda''_{r-1}$  to be the subsequence of  $\lambda_{r-1}$  containing all events to base objects that are accessed by  $p_n$  in  $\phi_r$ . We then define  $\alpha_r = \alpha_{r-1} \gamma'_r \lambda'_{r-1}$ ,  $\lambda_r = \lambda''_{r-1} e_r$  and show that  $\alpha_r \lambda_r \phi_r$  satisfies the properties of Definition 3.

We first observe that  $\alpha_r \lambda_r \phi_r$  is a well-defined execution, since the execution fragment  $\gamma'_r$  by  $p_{\ell_r}$  is performed after  $\alpha_{r-1}$ , and all operations in  $\lambda_{r-1}$  are nontrivial events to distinct base objects none of which is by  $p_{\ell_r}$ . It follows that  $\alpha_r \lambda_r$  and  $\alpha_{r-1} \gamma'_r e_r \lambda_{r-1}$  are indistinguishable to  $p_n$ , hence  $\phi_r$  is a solo execution of  $op_n$  by  $p_n$  after both executions.

Property 1 holds since  $\alpha_r \lambda_r$  is  $p_n$ -free by construction, and  $\phi_r$  is a solo execution fragment by  $p_n$  in which it performs  $op_n$ , so Property 2 holds. To show Property 3, we observe that  $\alpha_r \lambda_r$  is indistinguishable to  $p_n$  from  $\alpha_{r-1} \gamma'_r e_r \lambda_{r-1}$  and hence  $p_n$  accesses the base object  $B$  in  $\phi_r$ . Finally, Property 4 follows by construction.

We conclude the proof by claiming that  $\alpha_r \lambda_r$  is  $r$ -perturbing, which follows from its construction and Definition 2.  $\square$

Next, we prove a step lower bound for implementations that have an access-perturbation sequence. If the sequence is saturated, then the lower bound is linear in the number of processes, otherwise it is logarithmic in the length of the sequence. Our goal is to prove that  $p_n$  has to access a large number of base objects as it runs solo while performing an instance  $op_n$  of  $Op$  in one of the executions of  $op_n$ 's access-perturbation sequence. Let  $\pi_r$  denote the sequence of base objects accessed by  $p_n$  in  $\phi_r$ , in the order of their first access in  $\phi_r$ ;  $\pi_r$  is  $p_n$ 's solo path in  $\phi_r$ . If all the objects accessed in  $\lambda_{r-1}$  are also in  $\lambda_r$ , i.e.,  $p_n$  accesses them also in  $\phi_r$ , then

$\lambda_r = \lambda_{r-1}e_r$ . However, the application of  $e_r$  may have the undesirable effect (from the perspective of an adversary) of making  $\pi_r$  shorter than  $\pi_{r-1}$ :  $p_n$  may read the information written by  $p_{\ell_r}$  and avoid accessing some other objects that were previously in  $\pi_{r-1}$ .

To overcome this difficulty, we employ the *backtracking covering* technique, which is a quantitative version of a technique previous used in [5, 11]. The observation underlying this technique is that objects that are in  $\pi_{r-1}$  will be absent from  $\pi_r$  only if the additional object to which  $p_{\ell_r}$  applies the nontrivial event  $e_r$  precedes them in  $\pi_{r-1}$ . Thus the set of objects along  $\pi_r$  that are covered after  $\alpha_r\lambda_r$  is ‘closer’, in a sense, to the beginning of  $p_n$ ’s solo path in  $\phi_{r-1}$ . It follows that if there are many access-perturbation sequence executions  $r$  for which  $|\pi_r| < |\pi_{r-1}|$ , then one of the solo paths  $\pi_r$  must be ‘long’.

To capture this intuition, we define  $\Psi$ , a monotonically-increasing progress function of  $r$ .  $\Psi_r$  is a  $(\log L)$ -digit binary number defined as follows. Bit 0 (the most significant bit) of  $\Psi_r$  is 1 if and only if the first object in  $\pi_r$  is covered after  $\alpha_r$  (by one of the events of  $\lambda_r$ ); bit 1 of  $\Psi_r$  is 1 if and only if the second object in  $\pi_r$  exists and is covered after  $\alpha_r$ , and so on. Note that we do not need to consider paths that are longer than  $\log L$ . If such a path exists, the lower bound clearly holds.

To construct the  $r$ ’th access-perturbation sequence execution, we deploy a free process,  $p_{\ell_r}$ , and let it run solo until it is about to write to an uncovered object,  $O$ , along  $\pi_r$ . (Since the sequence is not saturated, it follows from Property 4(b) of Definition 3 that such  $p_{\ell_r}$  and  $O$  exist.) In terms of  $\Psi$ , this implies that the covering event  $e_r$  might flip some of the digits of  $\Psi_{r-1}$  from 1 to 0. But  $O$  corresponds to a more significant digit, and this digit is flipped from 0 to 1, hence  $\Psi_r > \Psi_{r-1}$  must hold. Thus we can construct executions  $\alpha_r\lambda_r\phi_r$ , for  $1 \leq r \leq L$ , in each of which  $\Psi_r$  increases. It follows that  $\Psi_r = L-1$  must eventually hold, implying that  $\pi_r$ ’s length is  $\Omega(\log L)$ .

**THEOREM 3.** *Let  $A$  be an  $n$ -process obstruction-free implementation of an  $L$ -perturbable object  $O$  from historyless primitives. Then  $A$  has an execution in which some process accesses  $\Omega(\min(\log L, n))$  distinct base objects during a single operation instance.*

**PROOF.** Lemma 2 establishes that every implementation of  $O$  from historyless primitives has an access-perturbation sequence of length  $L \geq 1$ ,  $\{\alpha_r\lambda_r\phi_r\}_{r=0}^L$ . If the sequence is saturated, then Definition 3 immediately implies that  $p_n$  accesses  $n-1$  distinct base objects in the course of performing  $\phi_r$ , and the lower bound holds. Otherwise, we show that  $op_n$  accesses  $\Omega(\log L)$  distinct base objects in one of these executions.

Let  $\pi_r = B_r^1 \dots B_r^{i_r}$  denote the sequence of all distinct base objects accessed by  $p_n$  in  $\phi_r$  (after  $\alpha_r\lambda_r$ ) according to Property 2 of Definition 3, and let  $S_{\pi_r}$  denote the set of these base objects. Let  $S_r^C = \{O_r^1, \dots, O_r^{j_r}\}$  be the set of base objects defined in Property 3 of Definition 3. Observe that, by Property 3,  $S_r^C \subseteq S_{\pi_r}$  holds. Without loss of generality, assume that  $O_r^1, \dots, O_r^{j_r}$  occur in  $\pi_r$  in the order of their superscripts.

In the execution  $\alpha_r\lambda_r\phi_r$ ,  $p_n$  accesses  $i_r$  distinct base objects. Thus, it suffices to show that some  $i_r$  is in  $\Omega(\log L)$ . For  $j \in \{1, \dots, i_r\}$ , let  $b_r^j$  be the indicator variable whose value is 1 if  $B_r^j \in S_r^C$  and 0 otherwise. We associate an in-

tegral progress parameter,  $\Psi_r$ , with each  $r \geq 0$ , defined as follows:

$$\Psi_r = \sum_{j=1}^{i_r} b_r^j \cdot \frac{L}{2^j}.$$

For simplicity of presentation, and without loss of generality, assume that  $L = 2^s$  for some integer  $s > 0$ , so  $s = \log L$ . If  $i_r > s$  for some  $r$  then we are done. Assume otherwise, then  $\Psi_r$  can be viewed as a binary number with  $s$  digits whose  $j$ ’th most significant bit is 1 if the  $j$ ’th base object in  $\pi_r$  exists and is in  $S_r^C$ , or 0 otherwise. This implies that the number of 1-bits in  $\Psi_r$  equals  $|S_r^C|$ . Our execution is constructed so that  $\Psi_r$  is monotonically increasing in  $r$  and eventually, for some  $r'$ ,  $\Psi_{r'}$  equals  $L-1 = L \sum_{j=1}^s \frac{1}{2^j}$ . This would imply that  $p_n$  accesses exactly  $s$  base objects during  $\phi_{r'}$  (after  $\alpha_{r'}\lambda_{r'}$ ).

We next show that  $\Psi_r > \Psi_{r-1}$ , for every  $0 < r \leq L$ . Since  $\alpha_{r-1}\lambda_{r-1}\phi_{r-1}$  is not saturated, by Property 4(b) of Definition 3, there is a process  $p_{\ell_r}$  that takes no steps in  $\lambda_{r-1}$ , and an execution fragment  $\gamma_r e_r$  of  $p_{\ell_r}$  after  $\alpha_{r-1}$ , such that  $e_r$  is the first nontrivial event of  $p_{\ell_r}$  in  $\gamma_r e_r$  to a base object in  $\{B_{r-1}^1, \dots, B_{r-1}^{i_{r-1}}\} \setminus \{O_{r-1}^1, \dots, O_{r-1}^{j_{r-1}}\}$ . By Property 2 of that definition, this object is accessed by  $p_n$  in  $\phi_r$ . Let  $k$  be the index of the object among the objects accessed in  $\phi_{r-1}$ , i.e., it is  $B_{r-1}^k$ . This implies that  $B_{r-1}^k \in S_{\pi_{r-1}} \setminus S_{r-1}^C$ .

As  $B_{r-1}^k \notin S_{r-1}^C$ , we have  $b_{r-1}^k = 0$ . Since  $e_r$  is the first nontrivial event of  $p_{\ell_r}$  in  $\gamma_r e_r$  to a base object in  $S_{\pi_{r-1}} \setminus S_{r-1}^C$ , we have that the values of objects  $B_{r-1}^1 \dots B_{r-1}^{k-1}$  are the same after  $\alpha_{r-1}\lambda_{r-1}$  and  $\alpha_r\lambda_r$ . It follows that  $b_r^j = b_{r-1}^j$  for  $j \in \{1, \dots, k-1\}$ . This implies, in turn, that  $B_{r-1}^k = B_r^k$ . As  $B_r^k \in S_r^C$ , we have  $b_r^k = 1$ . We get:

$$\begin{aligned} \Psi_r &= \sum_{j=1}^{i_r} b_r^j \cdot \frac{L}{2^j} \\ &= \sum_{j=1}^{k-1} b_r^j \cdot \frac{L}{2^j} + b_r^k \cdot \frac{L}{2^k} + \sum_{j=k+1}^{i_r} b_r^j \cdot \frac{L}{2^j} \\ &= \sum_{j=1}^{k-1} b_{r-1}^j \cdot \frac{L}{2^j} + \frac{L}{2^k} + \sum_{j=k+1}^{i_r} b_r^j \cdot \frac{L}{2^j} \\ &\geq \sum_{j=1}^{k-1} b_{r-1}^j \cdot \frac{L}{2^j} + \frac{L}{2^k} \\ &> \sum_{j=1}^{k-1} b_{r-1}^j \cdot \frac{L}{2^j} + \sum_{j=k+1}^{i_{r-1}} b_{r-1}^j \cdot \frac{L}{2^j} \\ &= \Psi_{r-1}, \end{aligned}$$

where the last equality is based on the observation that  $b_{r-1}^k = 0$ .

As  $\Psi_0 = 0$  and since  $\Psi_r$  strictly grows with  $r$  and can never exceed  $L-1$ , it follows that  $\Psi_L = L-1$ , which concludes the proof.  $\square$

Lemmas 1, 2 and Theorem 3 imply the following.

**THEOREM 4.** *An  $n$ -process obstruction-free implementation of an  $m$ -limited-use max register,  $m$ -limited-use counter,  $m$ -limited-use  $b$ -valued compare-and-swap object or an  $m$ -limited-use collect object from historyless primitives*

has an operation instance requiring  $\Omega(\min(\log m, n))$  steps. An obstruction-free implementation of a  $b$ -bounded max register from historyless primitives has an operation instance requiring  $\Omega(\min(\log b, n))$  steps.

An obstruction-free implementation of a  $k$ -additive-accurate  $m$ -limited-use counter from historyless primitives has an operation instance requiring  $\Omega(\min(\log m - \log k, n))$  steps.

To prove space-complexity lower bounds on  $L$ -perturbable objects, we construct perturbing sequences in which many objects are covered; not all of them are necessarily accessed by the reader, but, nevertheless, they must be distinct, giving a lower bound on the number of base objects. The proof of the next theorem appears in the full paper.

**THEOREM 5.** *The space complexity of an obstruction-free implementation of an  $m$ -limited-use max register or an  $m$ -limited-use collect object from historyless primitives is  $\Omega(\min(m, n))$ .*

*The space complexity of an obstruction-free implementation of an  $m$ -limited-use  $b$ -valued compare-and-swap object from historyless primitives is  $\Omega(\min(\sqrt[m]{m}, n))$ .*

*The space complexity of an obstruction-free implementation of a  $b$ -bounded max register from historyless primitives is  $\Omega(\min(b, n))$ .*

*The space complexity of an obstruction-free implementation of a  $k$ -additive-accurate  $m$ -limited-use counter from historyless primitives is  $\Omega(\min(\sqrt{\frac{m}{k}}, n))$ .*

### 3.2 Lower bounds for implementations using arbitrary primitives

The number of steps performed by an operation, as we have measured for implementations using only historyless objects, is not the only factor influencing the performance of an operation. The performance of a concurrent object implementation is also influenced by the extent to which multiple processes *simultaneously* access widely-shared memory locations. Dwork *et al.* [8] introduced a formal model to capture such contention, taking into consideration both the number of steps taken by a process and the number of *stalls* it incurs as a result of memory contention with other processes. More formally, an event  $e$  applied by a process  $p$  to object  $O$  in an execution  $\alpha$  incurs  $k$  memory stalls if it is immediately preceded by  $k$  events by distinct processes different from  $p$  that apply nontrivial primitives to  $O$ .

Our next result shows a lower bound on implementations using *arbitrary* read-modify-write primitives. Its proof employs an extension of the backtracking covering technique that uses a “bins-and-balls” argument. The proof of Theorem 3 uses access-perturbable sequence of executions, in which each new execution deploys a process to cover an object that is not covered in the preceding execution. Such a series of executions cannot, in general, be constructed for algorithms that may use arbitrary primitives. Instead, the proof constructs a series of executions in which each new execution deploys a process that covers *some* object along  $p_n$ 's path.

**DEFINITION 4.** *An access-stall perturbation sequence of length  $L$  of an operation instance  $op_n$  by process  $p_n$  on an object  $O$  is a sequence of executions  $\alpha_r \sigma_{r,1} \cdots \sigma_{r,j_r} \rho_r$ , such that  $\alpha_0$  is empty,  $j_0 = 0$ ,  $\rho_0$  is an execution of  $op_n$  by  $p_n$  starting from the initial configuration, and for every  $r$ ,  $1 \leq r \leq L$ , the following properties hold:*

1.  $\alpha_r$  is  $p_n$ -free,
2. in  $\rho_r$  process  $p_n$  runs solo until it completes the operation instance  $op_n$ ; in this instance,  $p_n$  accesses the base objects  $B_r^1, \dots, B_r^{i_r}$ ,
3. there is a subsequence  $O_r^1, \dots, O_r^{j_r}$  of disjoint objects in  $B_r^1, \dots, B_r^{i_r}$  and disjoint nonempty sets of processes  $S_r^1, \dots, S_r^{j_r}$  such that, for  $j = 1, \dots, j_r$ ,
  - each process in  $S_r^j$  covers  $O_r^j$  after  $\alpha_r$ , and
  - in  $\sigma_{r,j}$ , process  $p_n$  applies events until it is about to access  $O_r^j$  for the first time, then each of the processes in  $S_r^j$  accesses  $O_r^j$ , and, finally,  $p_n$  accesses  $O_r^j$ .
4. let  $\lambda_{r-1}$  be the subsequence of events by the processes in  $S_{r-1}^1 \cup \dots \cup S_{r-1}^{j_{r-1}}$  that are applied in  $\sigma_{r-1,1} \cdots \sigma_{r-1,j_{r-1}}$ , then  $\alpha_{r-1} \lambda_{r-1}$  is an  $r-1$ -perturbing execution; if  $\alpha_{r-1} \lambda_{r-1}$  is saturated, then we say that  $\alpha_{r-1} \sigma_{r-1,1} \cdots \sigma_{r-1,j_{r-1}} \rho_{r-1}$  is saturated,
5. If  $\alpha_{r-1} \sigma_{r-1,1} \cdots \sigma_{r-1,j_{r-1}} \rho_{r-1}$  is saturated, then the  $r$ 'th execution in the access-stall perturbation sequence is defined as identical to it. Otherwise, the following holds:  $O_r^{j_r} = B_{r-1}^k$ , for some  $1 \leq k \leq i_{r-1}$ ;  $B_r^i = B_{r-1}^i$ , for all  $i \in \{1, \dots, k\}$ ;  $O_r^i = O_{r-1}^i$  and  $S_r^i = S_{r-1}^i$  for all objects  $O_{r-1}^i$  that precede  $B_{r-1}^k$  in the sequence  $B_{r-1}^1, \dots, B_{r-1}^{i_{r-1}}$ ; and either  $B_{r-1}^k \notin \{O_{r-1}^1, \dots, O_{r-1}^{j_{r-1}}\}$  or  $O_r^{j_r} = O_{r-1}^{j_r}$  and  $|S_r^{j_r}| = |S_{r-1}^{j_r}| + 1$ .

The proof of the following lemma appears in the full paper.

**LEMMA 6.** *An  $L$ -perturbable object implementation has an access-stall perturbation sequence of length  $L$ .*

**THEOREM 7.** *Let  $A$  be an  $n$ -process obstruction-free implementation of an  $L$ -perturbable object  $O$  from read-modify-write primitives. Then  $A$  has an execution in which some process either accesses  $\Omega(\min(\log L, n))$  distinct base objects or incurs  $\Omega(\min(\log L, n))$  memory stalls, during a single operation instance.*

**PROOF.** For simplicity and without loss of generality, assume that  $L = 2^{2^s}$  for some integer  $s$ . If  $A$  has an execution in which some process accesses  $s$  distinct base objects during a single operation instance, then the theorem holds. Otherwise, Lemma 6 establishes that  $A$  has an access-stall perturbation sequence of length  $L$ . If one of these executions,  $\alpha_r \sigma_{r,1} \cdots \sigma_{r,j_r} \rho_r$ , for some  $r \leq L$ , is saturated, then it follows from Definition 4 that  $p_n$  incurs  $n-1$  memory stalls in the course of  $\sigma_{r,1} \cdots \sigma_{r,j_r}$  and the theorem holds. We therefore assume in the following that none of the executions in  $A$ 's access-stall perturbation sequence is saturated. We will prove that  $p_n$  incurs  $\Omega(s)$  memory stalls in one of these executions.

For  $i \in \{1, \dots, i_r\}$ , let variable  $n_r^i$  be defined as follows:

$$n_r^i = \begin{cases} |S_r^m|, & \text{if } \exists m \in \{1, \dots, j_r\} : B_r^i = O_r^m, \\ 0, & \text{otherwise.} \end{cases}$$

Let  $N_r = \sum_{i=1}^{i_r} n_r^i$ . Thus, it suffices for the proof to show that one of these executions has  $N_r = \Omega(s)$ . We associate

the following integral progress parameter,  $\Phi_r$ , with each execution  $r \geq 0$ :

$$\Phi_r = \sum_{i=1}^{i_r} n_r^i \cdot s^{s-i}.$$

If  $n_r^i \geq s - 1$  for some  $0 \leq r \leq L$  and  $i \in \{1, \dots, i_r\}$ , then we are done, since clearly  $N_r \geq s - 1$  holds in this case. Assume otherwise, then  $\Phi_r$  can be viewed as an  $s$ -digit number in base  $s$  whose  $i$ 'th most significant digit is 0 if  $i > i_r$  or equals the number of processes in  $S_r^1, \dots, S_r^{j_r}$  covering  $B_r^i$  after  $\alpha_r$ , otherwise.

From the last property of Definition 4,  $O_{r+1}^{j_{r+1}} = B_r^k$ , for some  $1 \leq k \leq i_r$  and, moreover,  $B_{r+1}^i = B_r^i$  for  $i \in \{1, \dots, k\}$ ,  $n_{r+1}^i = n_r^i$  for  $i \in \{1, \dots, k-1\}$ ,  $n_{r+1}^k = n_r^k + 1$ , and  $n_{r+1}^i = 0$  for  $i \in \{k+1, \dots, i_r\}$ . We get:

$$\begin{aligned} \Phi_{r+1} &= \sum_{i=1}^{i_{r+1}} n_{r+1}^i \cdot s^{s-i} \\ &= \sum_{i=1}^k n_{r+1}^i \cdot s^{s-i} \\ &= \sum_{i=1}^{k-1} n_r^i \cdot s^{s-i} + (n_r^k + 1) \cdot s^{s-k} \\ &> \sum_{i=1}^k n_r^i \cdot s^{s-i} + \sum_{i=k+1}^s (s-1) \cdot s^{s-i} \\ &\geq \sum_{i=1}^{i_r} n_r^i \cdot s^{s-i} \\ &= \Phi_r \end{aligned}$$

Since the sequence  $\Phi_1, \dots, \Phi_L$  is strictly growing, each  $\Phi_r$  is unique. By the definition of  $\Phi$ , each value  $\Phi_r$  corresponds to a different partitioning of integer  $N_r$  to the values of the  $s$  digits of  $\Phi_r$ . What is the maximum number  $\mathcal{N}$  of different executions  $r$  for which  $N_r \leq s$  holds?  $\mathcal{N}$  is at most the number of distinguishable partitions of up to  $s$  identical balls into  $s$  bins. Let  $A_{b,c}$  be the number of distinguishable partitions of  $b$  identical balls into  $c$  bins, then:

$$\begin{aligned} \mathcal{N} &\leq \sum_{j=0}^s A_{j,s} \\ &= A_{s,s+1} \\ &= \binom{2s}{s} \\ &= \binom{\log L}{\log L/2} \\ &= \Theta\left(\frac{4^{\log L/2}}{\sqrt{\pi \log L/2}}\right) \\ &= \Theta\left(\frac{L}{\sqrt{\pi \log L/2}}\right) \\ &< L. \end{aligned}$$

Where the penultimate equality above follows from Stirling's approximation and the fact that the error of the approximation ratio  $\binom{\log L}{\log L/2} / \frac{4^{\log L/2}}{\sqrt{\pi \log L/2}}$  is inversely propor-

tional to  $s$  [9, page 75]. Thus, for all  $L \geq 4$ , there is an execution  $\alpha_{r'} \sigma_{r',1} \dots \sigma_{r',j_{r'}} \rho_{r'}$  such that  $N_{r'} > s$  holds.  $\square$

Lemma 1 and Theorem 7 yield the following specific bounds.

**THEOREM 8.** *An  $n$ -process obstruction-free implementation of an  $m$ -limited-use max register,  $m$ -limited-use counter, an  $m$ -limited-use  $b$ -valued compare-and-swap object or an  $m$ -limited-use collect object from read-modify-write primitives has an operation instance that either requires  $\Omega(\min(\log m, n))$  steps or incurs  $\Omega(\min(\log m, n))$  stalls.*

*An obstruction-free implementation of a  $b$ -bounded max register from read-modify-write primitives has an operation instance that either requires  $\Omega(\min(\log b, n))$  steps or incurs  $\Omega(\min(\log b, n))$  stalls.*

*An obstruction-free implementation of a  $k$ -additive-accurate  $m$ -limited-use counter from read-modify-write primitives has an operation instance that either requires  $\Omega(\min(\log m - \log k, n))$  steps or incurs  $\Omega(\min(\log m - \log k, n))$  stalls.*

## 4. LOWER BOUND FOR RANDOMIZED APPROXIMATE COUNTERS

Proving lower bounds for *randomized* implementations of concurrent objects is more difficult, due to the extra flexibility these implementations have. We were not able to prove general lower bounds for a class of objects, but we take a first step in this direction by proving a lower bound for a specific, but very useful, object, namely an approximate counter. This object allows some error in the operations applied to them. We consider two variants, depending on whether the error is additive or multiplicative.

We assume an *oblivious adversary*, which fixes the sequence of process steps in advance, without being able to predict the coin-flips of the processes or the progress of the execution; in fact, our adversary does not even require knowledge of the implementation, allowing us to prove the lower bound using Yao's Principle [16]. We consider *deterministic algorithms*, since a randomized algorithm can be seen as a weighted average of deterministic ones. A distribution over schedules that gives a high cost on average for any fixed deterministic algorithm, also gives a high cost on average for any randomized algorithm, which also implies that there exists some specific schedule that does so. We will describe an (oblivious) adversary strategy achieving the next lower bound:

**THEOREM 9.** *For a randomized implementation of an  $m$ -valued  $c$ -multiplicative-accurate counter using historyless primitives for  $n \geq m$  processes, a fixed  $\epsilon > 0$ , and  $w > 0$ , there is an oblivious adversary strategy that yields, with probability at least  $1 - \epsilon$ , an execution consisting of at most  $m - 1$  concurrent **CounterIncrement** operation instances, some of which may be incomplete, followed by a **CounterRead** operation instance, in which one of the following conditions holds: (a) a constant fraction of the **CounterIncrement** instances take more than  $w$  operations; (b) the value returned by the **CounterRead** operation instance is not consistent with any linearization of the completed operation instances; or (c) the **CounterRead** operation instance takes  $\Omega\left(\frac{\log \log m - \log \log c}{\log w}\right)$  operations.*

We first consider a schedule constructed as follows. Process  $p_1$  carries out an operation  $\beta_1$  for at most  $w$  steps. With

probability  $p$  for each step,  $p_1$  is stopped early and is suspended before it can carry the step out; if the step is not a read operation, this means that the target register is now covered by a pending operation that can be delivered later to overwrite any subsequent work by other processes. Whether  $p_1$  completes its operation or not, process  $p_2$  is next scheduled to carry out at most  $w$  steps, each of which causes  $p_2$  to be suspended with probability  $p$  as before, and this process is repeated for the remaining processes up through  $p_{n-1}$ . In this way we assemble a schedule  $\Gamma = \beta'_1\beta'_2\dots\beta'_{n-1}$ , where each  $\beta'_i$  is an initial prefix of some high-level operation  $\beta_i$ .

Let  $r$  be chosen arbitrarily. From  $\Gamma$ , we construct a family of schedules  $\{\Xi_k\}_{k \geq 0}$ , where each  $\Xi_k$  consists of an initial prefix of  $\Gamma$  of length  $k$  (i.e., consisting of  $k$  steps), followed by the delivery of all delayed operations from  $\Gamma$ , and in turn followed by the first  $r$  steps of a single operation  $\alpha$  executed by  $p_n$ . Thus each  $\Xi_k$  is of the form  $\beta'_1\beta'_2\dots\beta'_{m-1}\beta''_m\delta_m\delta_{m-1}\dots\delta_1\alpha$ , where  $\delta_i$  is either the delayed operation of  $i$  or the empty sequence if there is no such operation,  $\alpha$  is the single operation of  $p_n$ , and  $\beta''_m$  is a prefix of  $\beta_m$  of length  $k - |\beta'_1\beta'_2\dots\beta'_{m-1}|$ .

The proof is based first on bounding the number of distinct values returned by the reader across all the schedules  $\Xi_k$  as a function of  $p$  and  $r$ , and then showing that we can select a subset of these schedules that must either violate the restriction to short increment and read operations or return significantly more distinct values. This implies that choosing one of these schedules uniformly at random is likely to hit one of the bad outcomes. The next lemma bounds the number of distinct return values, and its proof appears in the full paper.

LEMMA 10. *Among the schedules  $\Xi_k$  above,  $\alpha$  returns at most  $(1+1/p)^r$  distinct values on average, where the average is taken over the random choices of the adversary for when to delay operations.*

The key idea is that because  $\alpha$  is deterministic, the value it returns can depend only on the values of the at most  $r$  registers it reads, and that each register will get at most  $1 + 1/p$  values on average in all the  $\Xi_k$  before it becomes covered by some  $\delta_i$ . This is essentially the same idea as used in [3] for max registers, except that we provide a more careful analysis of the dependence between the number of values found in each registers, because the union bound used in [3] reduces the lower bound by a  $\Theta(\log \log m)$  factor that in our case would eliminate the lower bound completely.

Lemma 10 holds for arbitrary sequences of operations. To prove Theorem 9, we show that for the specific case where  $p = 1/4w$  and each  $\beta_i$  is a **CounterIncrement** and  $\alpha$  is a **CounterRead** for a  $c$ -multiplicative-accurate counter, we can pick out a subfamily of executions  $\Xi_{k_0}, \Xi_{k_1}, \dots, \Xi_{k_{\ell-1}}$ , where  $\ell - 1 = \lfloor \frac{1}{2} \log_{2c} \sqrt{m} \rfloor - 1 = \Theta(\log m / \log c)$ , such that, on average, a constant fraction of the executions  $\Xi_{k_i}$  satisfies one of the conditions in Theorem 9. A detailed proof appears in the full paper.

If we choose  $w$  to match the lower bound on **CounterRead**, we get a lower bound on the worst-case cost of a  $c$ -multiplicative-accurate counter operation for fixed  $c$  of  $\Omega\left(\frac{\log \log m - \log \log c}{\log \log \log m}\right)$ . This is much smaller than Jayanti's lower bound of  $\Omega(\log n)$  on randomized  $n$ -bounded counters [14], which also allows much stronger primitives in the implementation. But the smaller bound is not surprising if

one considers that, for any constant  $c$ , a  $c$ -multiplicative-accurate counter effectively provides only  $\Theta(\log \log m)$  bits of information about the number of increments, compared with  $\Theta(\log m)$  for standard counter.

## 5. SUMMARY

This paper presents lower bounds for concurrent obstruction-free implementations of objects that are used in a restricted manner. (See Table 1 in the introduction.)

The step lower-bound on max registers is tight [3] and the step lower bound on randomized counters is almost tight, as there is an  $O(\log \log m)$  upper bound [7], under the same adversary model. It is unclear whether the other lower bounds are tight.

Another interesting research direction is to devise generic implementations for  $L$ -perturbable objects. This is of particular interest in the case of randomized implementations, where there is also an important issue of the type of adversary tolerated.

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