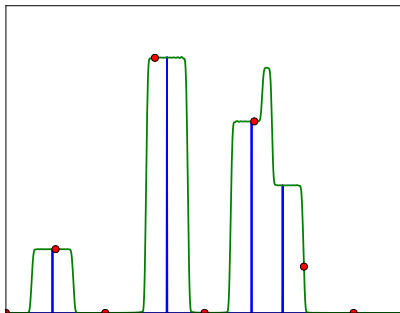


Sparse Fourier Transform Algorithms

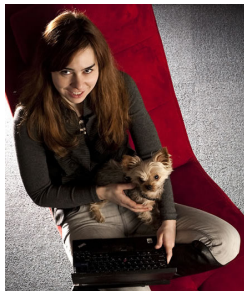
Eric Price

MIT

2013-2-17



Collaboration with Rest of Session Speakers



Outline

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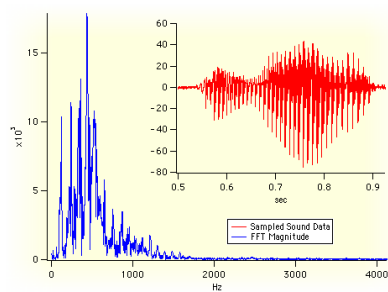
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Discrete Fourier Transform (DFT)

- Given $x \in \mathbb{C}^n$, compute Fourier transform \hat{x} :

$$\hat{x}_i = \sum_j \omega^{ij} x_j \quad \text{for } \omega = e^{2\pi i/n}$$

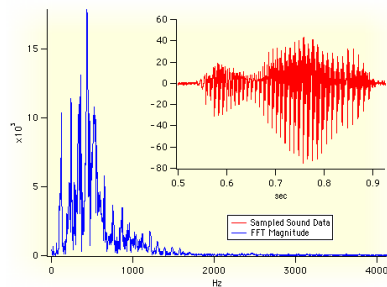


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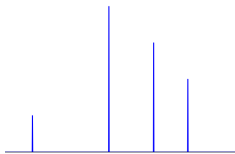
$$\hat{x}_i = \sum_j \omega^{ij} x_j \quad \text{for } \omega = e^{2\pi i/n}$$

$$\hat{x} = Fx \quad \text{for } F_{ij} = \omega^{ij}$$



Sparse Fourier Transform

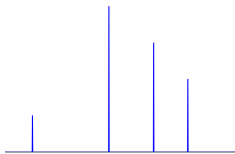
Exact Sparsity



- Suppose \hat{x} is k -sparse: only k non-zero coefficients.

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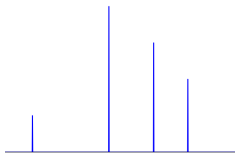
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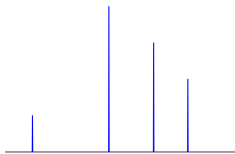
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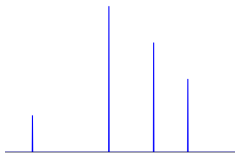


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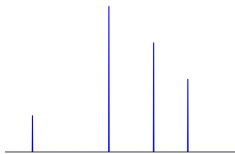


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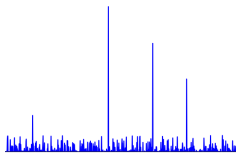
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Sparse Fourier Transform

Exact Sparsity



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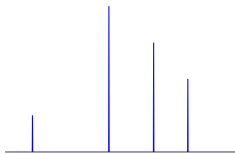


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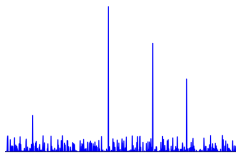
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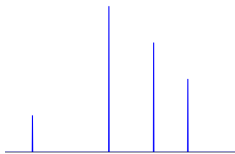


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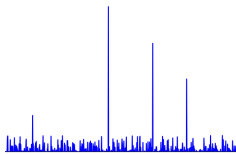
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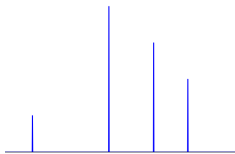


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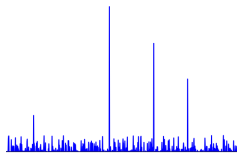
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Sparse Fourier Transform

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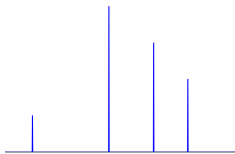
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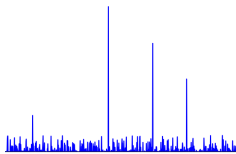
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- Faster than FFT for any $k \ll n$.

Previous work on Sparse Fourier Transforms

- Boolean cube: [KM92], [GL89]. \mathbb{C}^n : [Mansour '92] $k^c \log^c n$.
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 - ▶ If no hidden constants, would be 100x faster at 0.1%.

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- Faster than FFT whenever $k/n < C$ for fixed constant C .
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- Caveats:
 - ▶ Output $\hat{\mathbf{x}}$ has $\log n$ bit precision.
 - ▶ n must be a power of 2 (more generally, n must be smooth).
 - ▶ Succeed with 90% probability.

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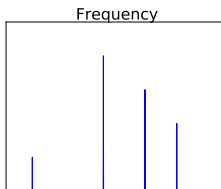
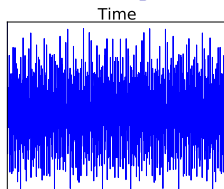
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- Then: repeat on residual, with $k \rightarrow k/2$ and decreasing the error probability.

What can you do with Fourier measurements?

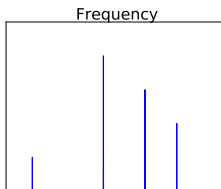
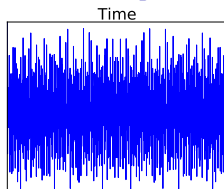


n -dimensional DFT:

$O(n \log n)$

$x \rightarrow \hat{x}$

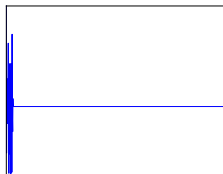
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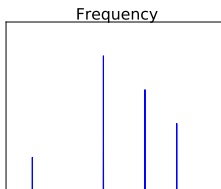
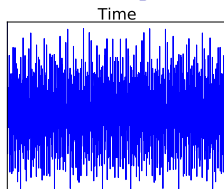
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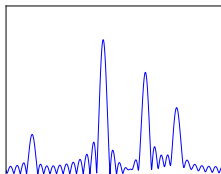
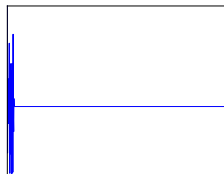
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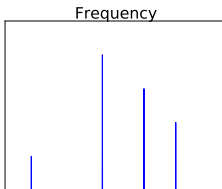
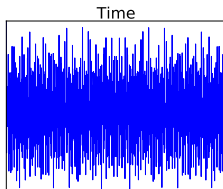
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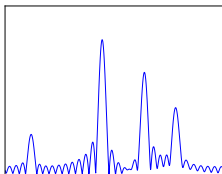
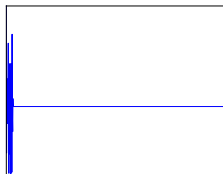
n -dimensional DFT of first B terms: $O(n \log n)$

$x \cdot \text{boxcar} \rightarrow \hat{x} * \text{sinc}$.

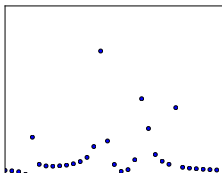
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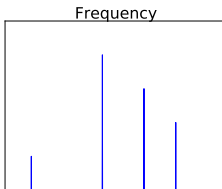
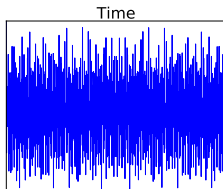


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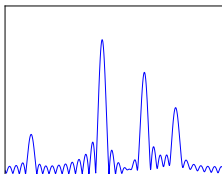
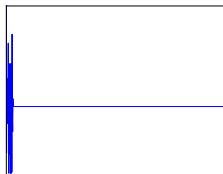


B -dimensional DFT of first B terms: $O(B \log B)$
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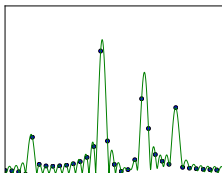
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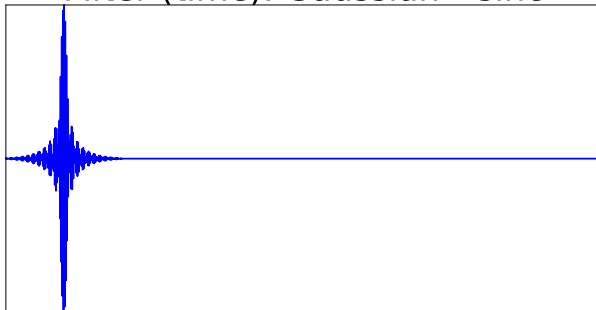
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A Better Filter

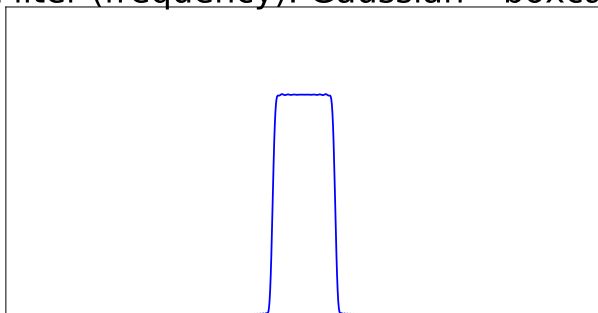
Filter (time): Gaussian \cdot sinc



- Time domain is $O(B \log n)$ sparse.

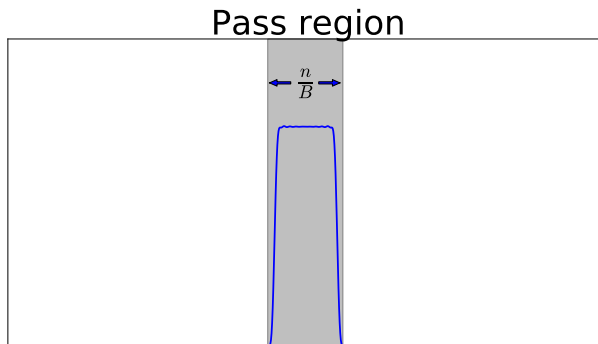
A Better Filter

Filter (frequency): Gaussian * boxcar



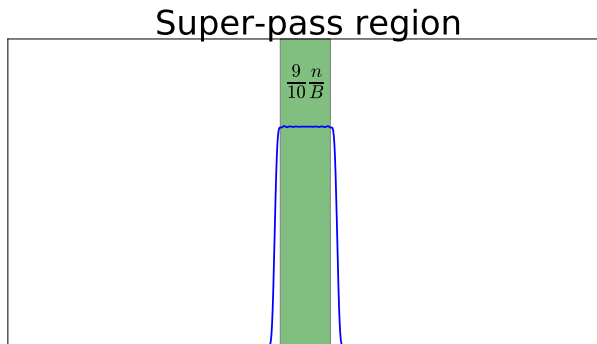
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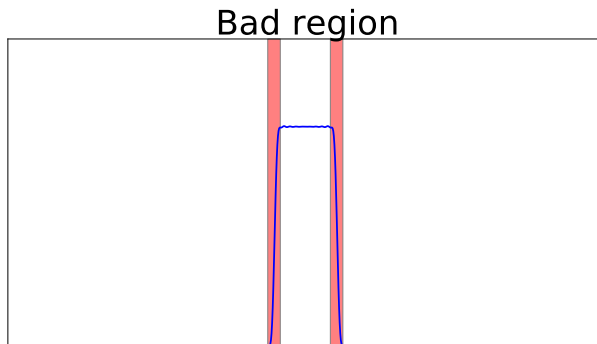
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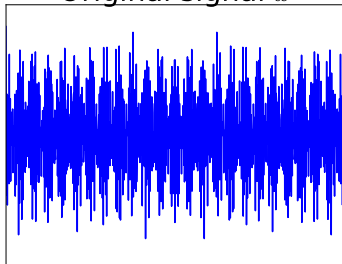
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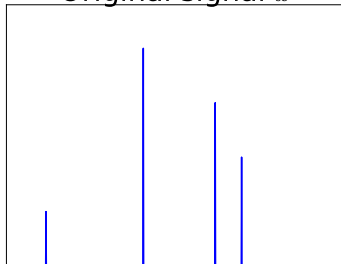
- Time domain is $O(B \log n)$ sparse.
- “Pass region” of size n/B , outside which filter is negligible δ .
- “Super-pass region”, where filter ≈ 1 .
- Small fraction (say 10%) is “bad region” with intermediate value.

Algorithm for *exactly sparse* signals

Original signal x

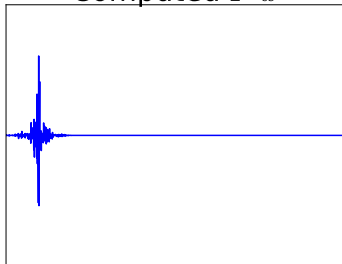


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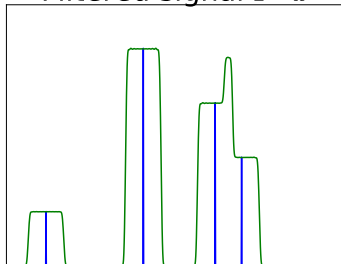


Algorithm for *exactly* sparse signals

Computed $F \cdot x$



Filtered signal $\widehat{F} * \widehat{x}$

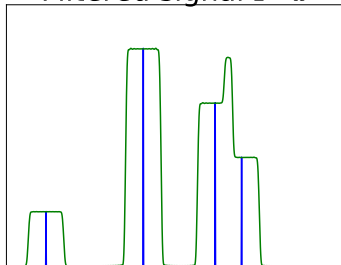


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$F \cdot x$ aliased to B terms



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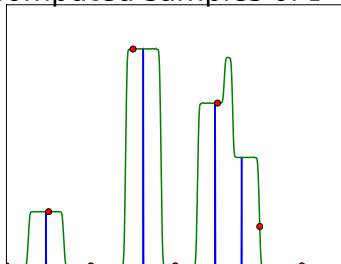


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Computed samples of $\widehat{F} * \widehat{x}$

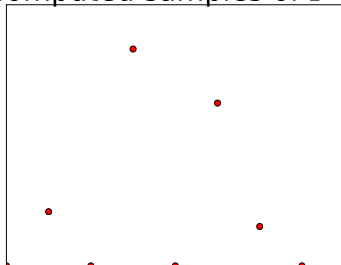


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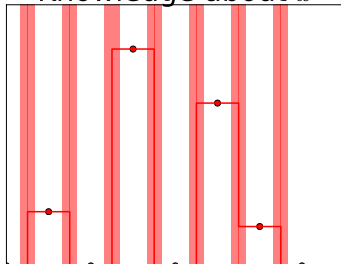


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Knowledge about \hat{x}

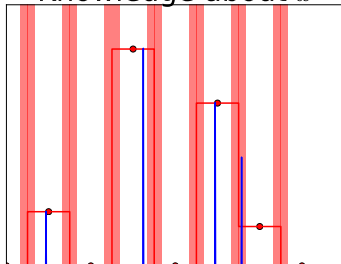


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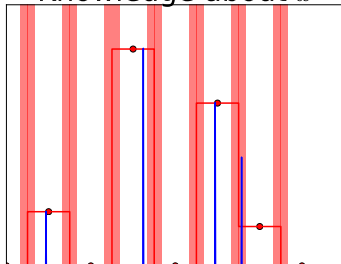


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If i is isolated in its bucket and in the “super-pass” region, the value b we compute for its bucket satisfies

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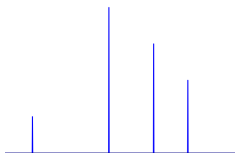
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- Gives $O(k \log n)$ time sparse Fourier transform. □

Outline

- 1 Introduction
- 2 Algorithm (exactly sparse case)
- 3 Algorithm (noisy case)**

Approximate sparsity

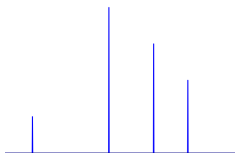
Exact Sparsity



Our Result: $O(k \log n)$

Approximate sparsity

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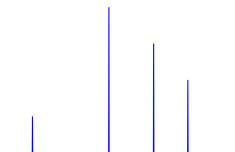


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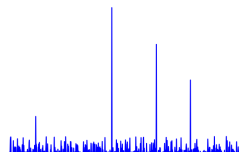
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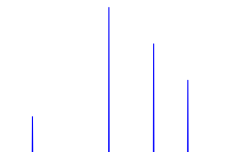


$O(k \log(n/k) \log n)$

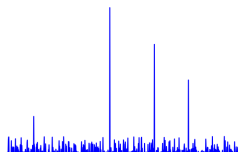
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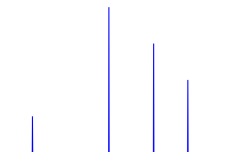
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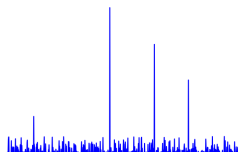
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Approximate Sparsity



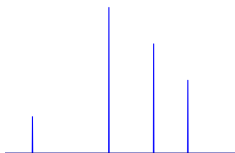
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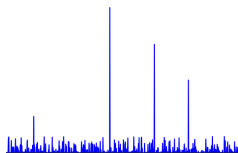
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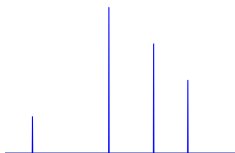
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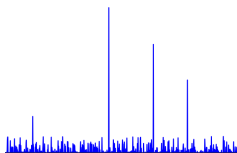
- What if there's mass outside top k elements x_k ?
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Approximate sparsity

Exact Sparsity



Approximate Sparsity



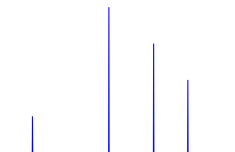
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$O^*(k \log_{1+SNR}(n/k) \log n)$

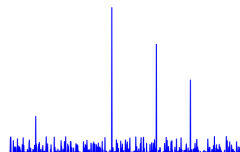
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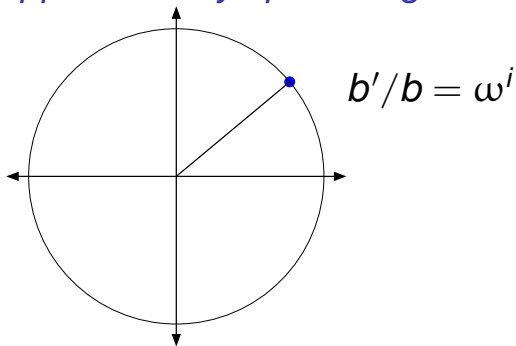


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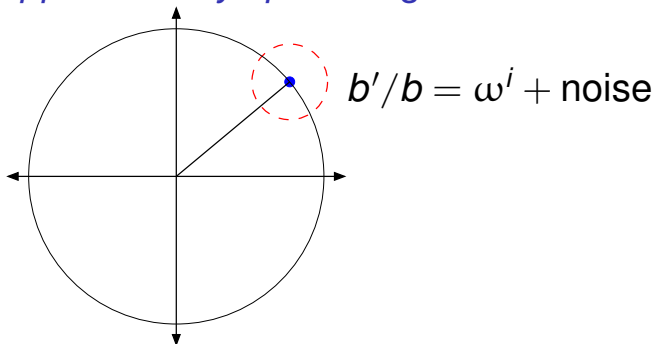
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Algorithm for *approximately sparse signals*



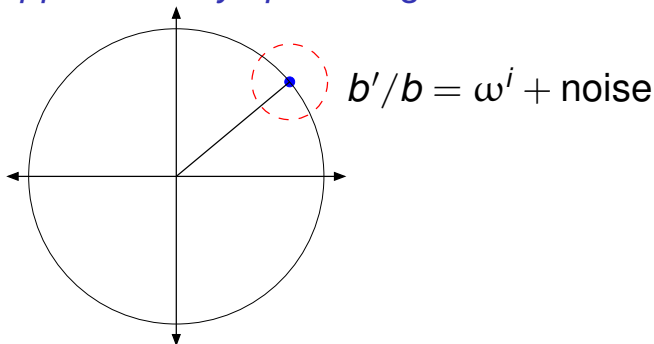
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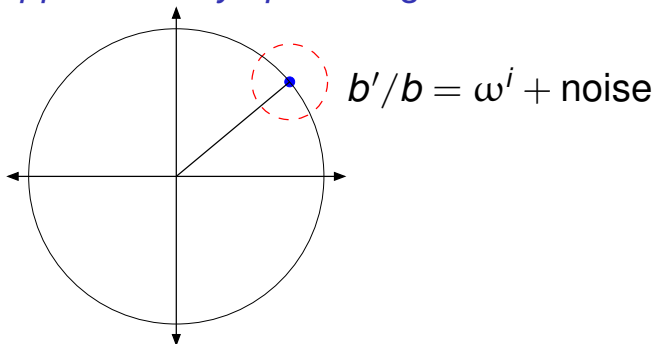
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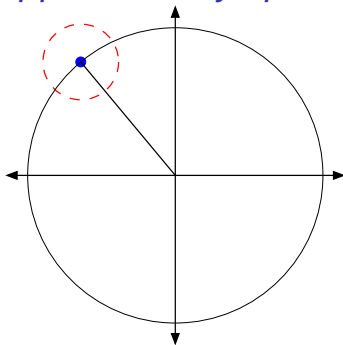
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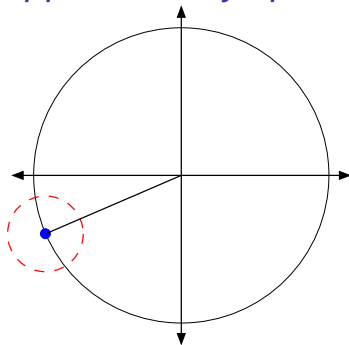
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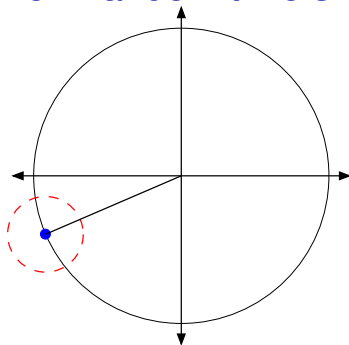
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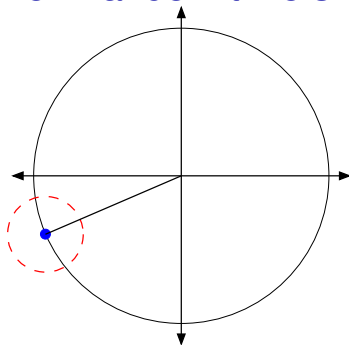
Recovering i from random time shifts c



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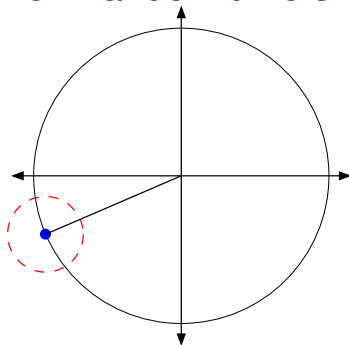
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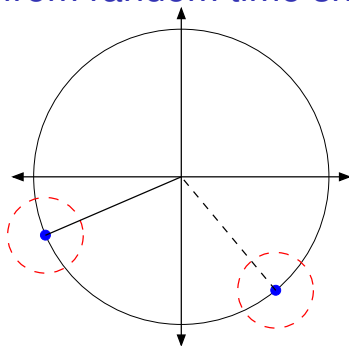
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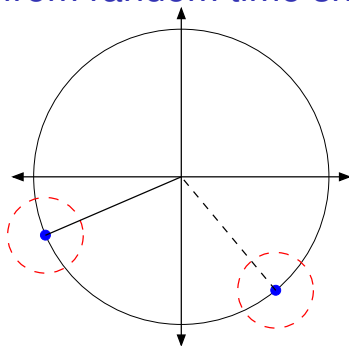
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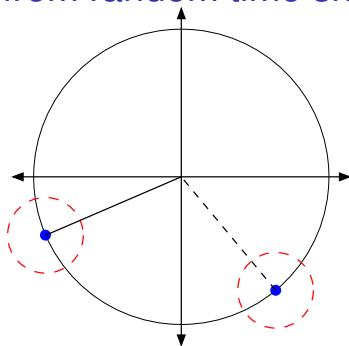
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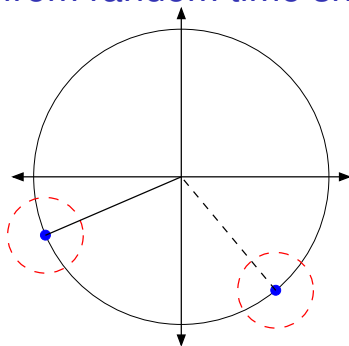
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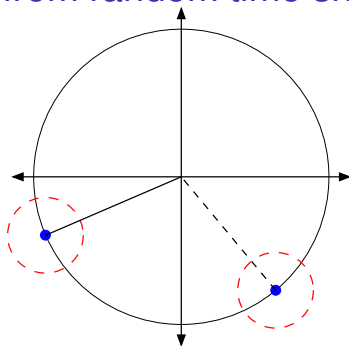
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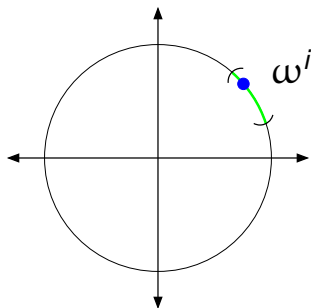
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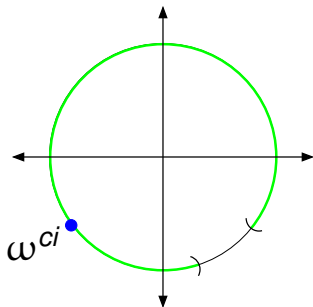
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 - ▶ Constant rate, quadratic decoding time.

Recover high order bits in sequence



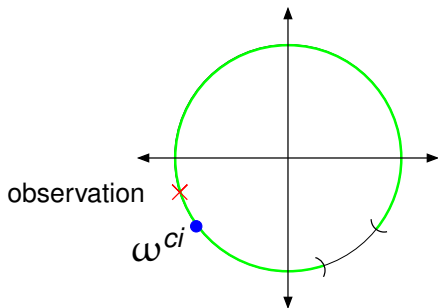
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Recover high order bits in sequence



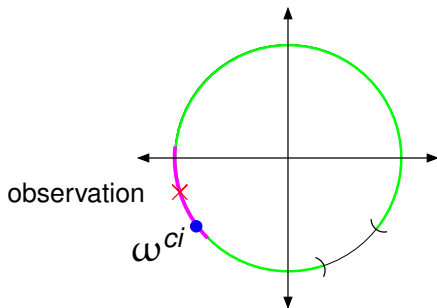
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Recover high order bits in sequence



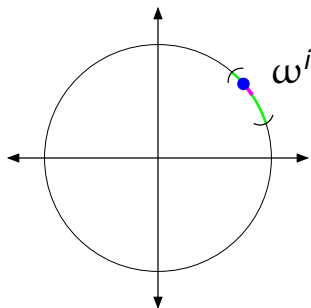
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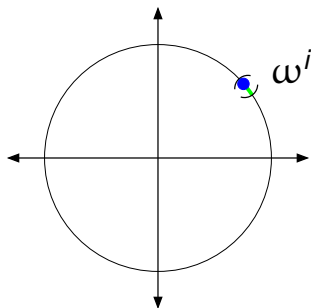
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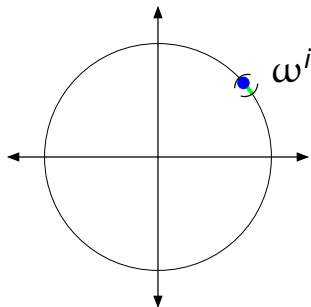
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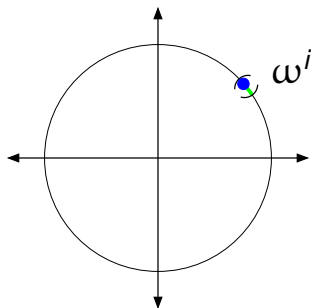
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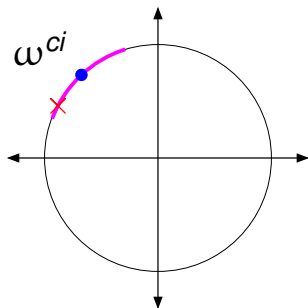
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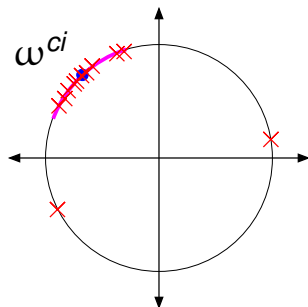
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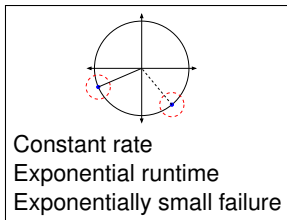
Recover high order bits in sequence



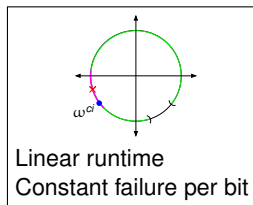
- Want to find i in contiguous region of size $R = n/k$.
- Choose $c \approx n/R$ so possibilities cover most of circle.
- Observation identifies i inside constant fraction of region.
- Restrict and repeat, $O(\log(n/k))$ times.
- Linear decoding time.
 - ▶ But rate isn't constant, just $1/\log \log(n/k)$...

Combining the two approaches

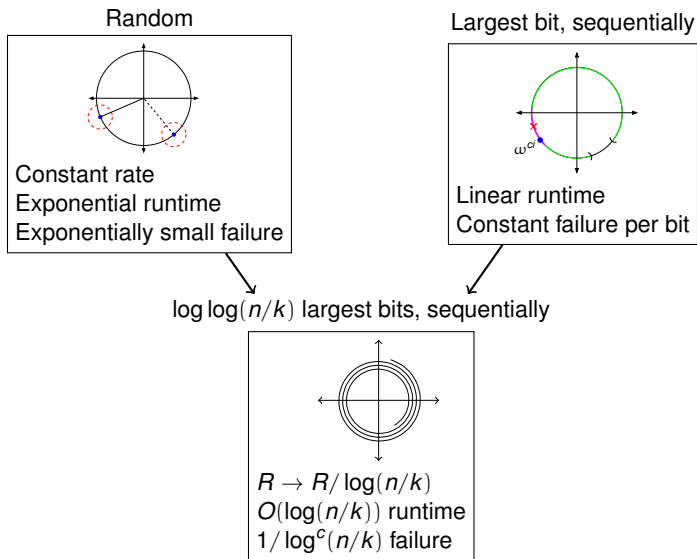
Random



Largest bit, sequentially

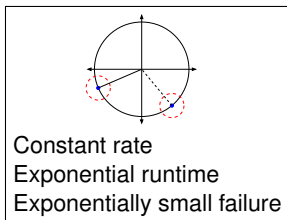


Combining the two approaches

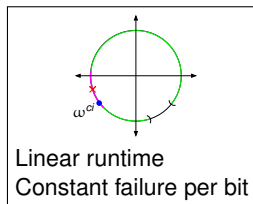


Combining the two approaches

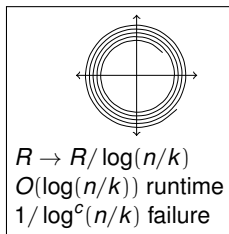
Random



Largest bit, sequentially

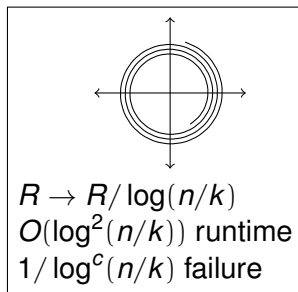


$\log \log(n/k)$ largest bits, sequentially



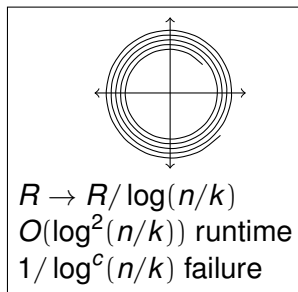
Our Decoding Procedure

$\log \log(n/k)$ largest bits, sequentially



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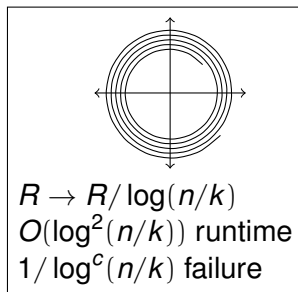
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Our Decoding Procedure

$\log \log(n/k)$ largest bits, sequentially



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- Gives $O(k \log(n/k) \log n)$ time/sample complexity.

Conclusion

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