





















































	Centralized Planner	Distributed Planner
Candidate Generation	Nc	Nc
Temporal Consistency Checking	NE ≈ N <sup>2</sup>	Ne
Overall Time Complexity	Exponential	Exponential
X7 X7 1	6 I	
N Number	er of nodes	
e Numb	er of local edges	
C Size of	f domain of choice variable	s

