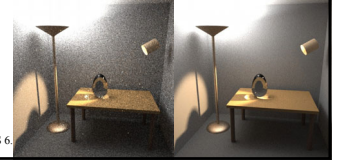
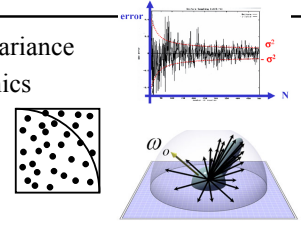


Curves & Surfaces

Last Time:

- Expected value and variance
- Monte-Carlo in graphics
- Importance sampling
- Stratified sampling
- Path Tracing
- Irradiance Cache
- Photon Mapping



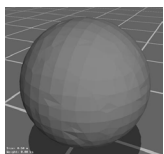
Questions?

Today

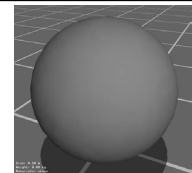
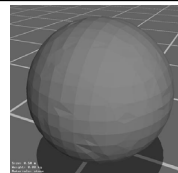
- **Motivation**
 - Limitations of Polygonal Models
 - Gouraud Shading & Phong Normal Interpolation
 - Some Modeling Tools & Definitions
- Curves
- Surfaces / Patches
- Subdivision Surfaces

Limitations of Polygonal Meshes

- Planar facets (& silhouettes)
- Fixed resolution
- Deformation is difficult
- No natural parameterization (for texture mapping)

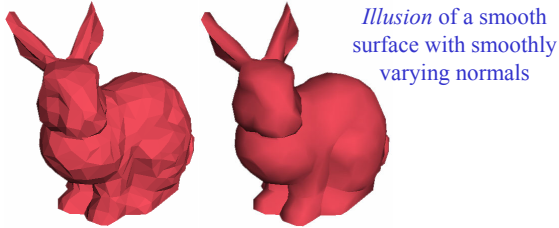


Can We Disguise the Facets?



Gouraud Shading

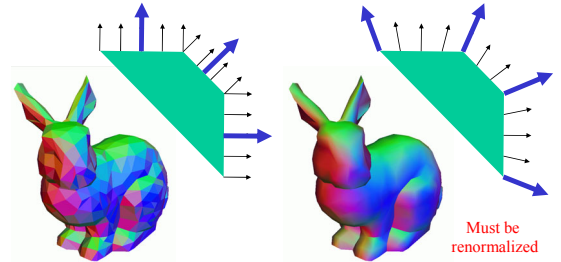
- Instead of shading with the normal of the triangle, shade the vertices with the *average normal* and interpolate the color across each face



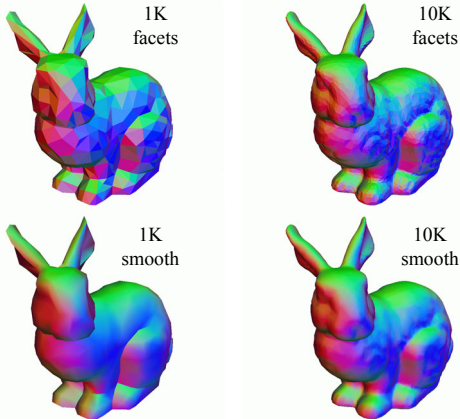
MIT EECS 6.837, Durand and Cutler

Phong Normal Interpolation (Not Phong Shading)

- Interpolate the average vertex normals across the face and compute *per-pixel shading*



MIT EECS 6.837, Durand and Cutler



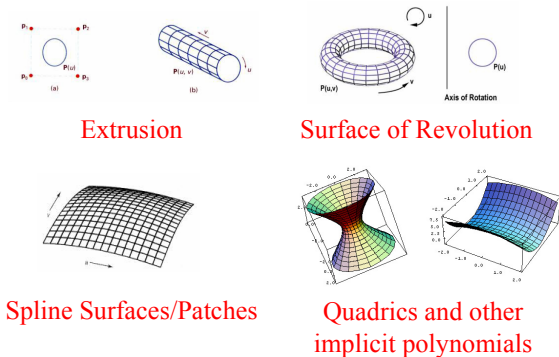
Better, but not always good enough

- Still low, fixed resolution (missing fine details)
- Still have polygonal silhouettes
- Intersection depth is planar (e.g. ray visualization)
- Collisions problems for simulation
- Solid Texturing problems
- ...



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Some Non-Polygonal Modeling Tools



Continuity definitions:

- C^0 continuous
 - curve/surface has no breaks/gaps/holes
- G^1 continuous
 - tangent at joint has same direction
- C^1 continuous
 - curve/surface derivative is continuous
 - tangent at joint has same direction *and* magnitude
- C^n continuous
 - curve/surface through n^{th} derivative is continuous
 - important for shading



MIT EECS 6.837, Durand and Cutler

Questions?

MIT EECS 6.837, Durand and Cutler

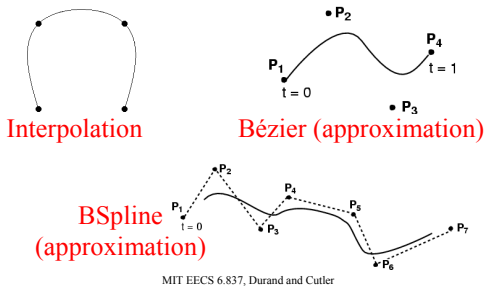
Today

- Motivation
- Curves
 - What's a Spline?
 - Linear Interpolation
 - Interpolation Curves vs. Approximation Curves
 - Bézier
 - BSpline (NURBS)
- Surfaces / Patches
- Subdivision Surfaces

MIT EECS 6.837, Durand and Cutler

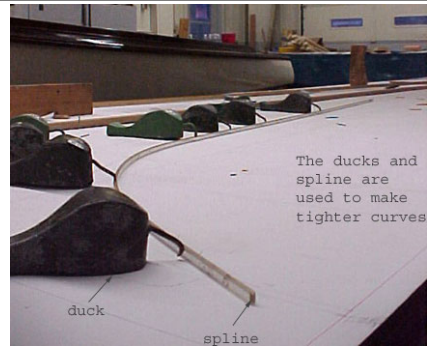
Definition: What's a Spline?

- Smooth curve defined by some control points
- Moving the control points changes the curve



MIT EECS 6.837, Durand and Cutler

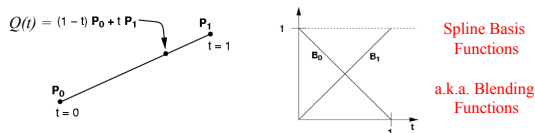
Interpolation Curves / Splines



www.abm.org

Linear Interpolation

- Simplest "curve" between two points



$$Q(t) = \begin{pmatrix} Q_x(t) \\ Q_y(t) \\ Q_z(t) \end{pmatrix} = ((P_0) (P_1)) \begin{pmatrix} -1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} t \\ 1 \end{pmatrix}$$

$$Q(t) = \mathbf{GBT}(t) = \text{Geometry } \mathbf{G} \cdot \text{Spline Basis } \mathbf{B} \cdot \text{Power Basis } \mathbf{T}(t)$$

MIT EECS 6.837, Durand and Cutler

Interpolation Curves

- Curve is constrained to pass through all control points
- Given points P_0, P_1, \dots, P_n , find lowest degree polynomial which passes through the points

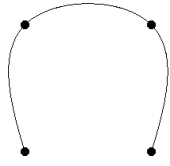
$$x(t) = a_{n-1}t^{n-1} + \dots + a_2t^2 + a_1t + a_0$$

$$y(t) = b_{n-1}t^{n-1} + \dots + b_2t^2 + b_1t + b_0$$

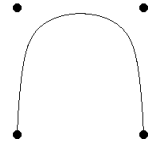
$$Q(t) = \mathbf{GBT}(t) = \text{Geometry } \mathbf{G} \cdot \text{Spline Basis } \mathbf{B} \cdot \text{Power Basis } \mathbf{T}(t)$$

MIT EECS 6.837, Durand and Cutler

Interpolation vs. Approximation Curves



Interpolation
curve must pass through control points

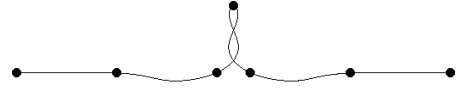


Approximation
curve is influenced by control points

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Interpolation vs. Approximation Curves

- Interpolation Curve – over constrained → lots of (undesirable?) oscillations



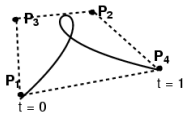
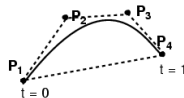
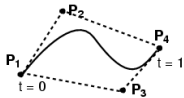
- Approximation Curve – more reasonable?



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Cubic Bézier Curve

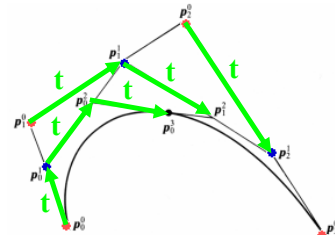
- 4 control points
- Curve passes through first & last control point
- Curve is tangent at P_0 to (P_0-P_1) and at P_4 to (P_4-P_3)



A Bézier curve is bounded by the convex hull of its control points.

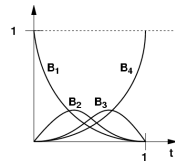
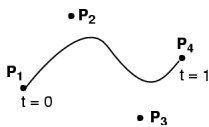
Cubic Bézier Curve

- de Casteljau's algorithm for constructing Bézier curves



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Cubic Bézier Curve



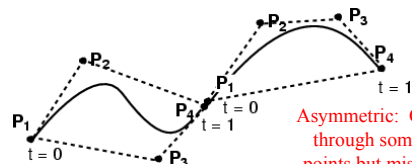
$$Q(t) = (1-t)^3 P_1 + 3t(1-t)^2 P_2 + 3t^2(1-t) P_3 + t^3 P_4$$

$$Q(t) = \text{GBT}(t) \quad B_{\text{Bezier}} = \begin{pmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 3 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

Bernstein Polynomials

$$B_1(t) = (1-t)^3; B_2(t) = 3t(1-t)^2; B_3(t) = 3t^2(1-t); B_4(t) = t^3$$

Connecting Cubic Bézier Curves

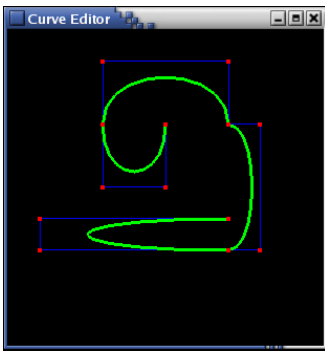


Asymmetric: Curve goes through some control points but misses others

- How can we guarantee C^0 continuity?
- How can we guarantee G^1 continuity?
- How can we guarantee C^1 continuity?
- Can't guarantee higher C^2 or higher continuity

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Connecting Cubic Bézier Curves



MIT EECS 6.837, Durand and Cutler

- Where is this curve
 - C^0 continuous?
 - G^1 continuous?
 - C^1 continuous?
- What's the relationship between:
 - the # of control points, and
 - the # of cubic Bézier subcurves?

Higher-Order Bézier Curves

- > 4 control points
- Bernstein Polynomials as the basis functions

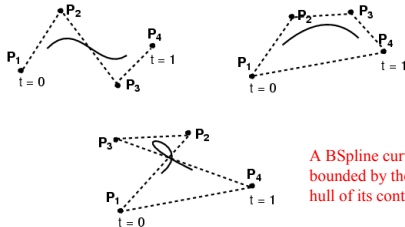
$$B_i^n(t) = \frac{n!}{i!(n-i)!} t^i (1-t)^{n-i}, \quad 0 \leq i \leq n$$

- Every control point affects the entire curve
 - Not simply a local effect
 - More difficult to control for modeling

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Cubic BSplines

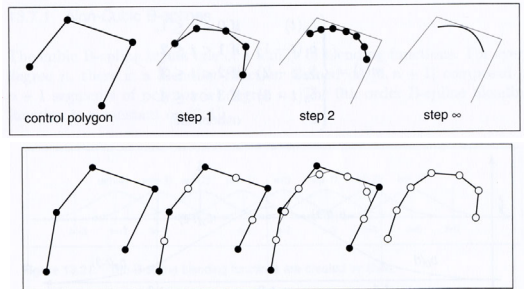
- ≥ 4 control points
- Locally cubic
- Curve is not constrained to pass through any control points



A BSpline curve is also bounded by the convex hull of its control points.

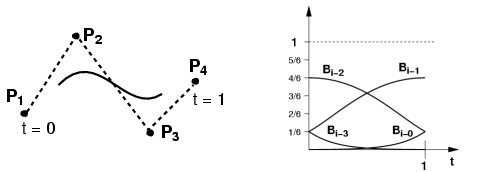
Cubic BSplines

- Iterative method for constructing BSplines



Shirley, Fundamentals of Computer Graphics

Cubic BSplines



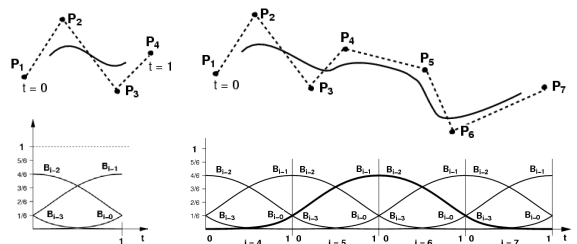
$$Q(t) = \frac{(1-t)^3}{6} P_{i-3} + \frac{3t^3 - 6t^2 + 4}{6} P_{i-2} + \frac{-3t^3 + 3t^2 + 3t + 1}{6} P_{i-1} + \frac{t^3}{6} P_i$$

$$Q(t) = \mathbf{GBT}(t) \quad B_{B-Spline} = \frac{1}{6} \begin{pmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 0 & 4 \\ -3 & 3 & 3 & 1 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

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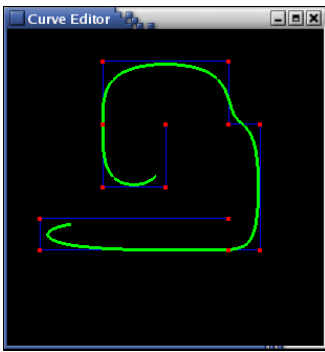
Cubic BSplines

- Can be chained together
- Better control locally (windowing)



MIT EECS 6.837, Durand and Cutler

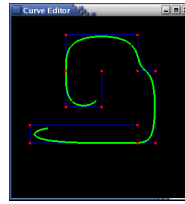
Connecting Cubic BSpline Curves



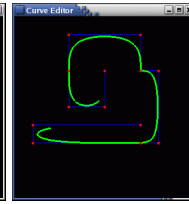
MIT EECS 6.837, Durand and Cutler

- What's the relationship between
 - the # of control points, and
 - the # of cubic BSpline subcurves?

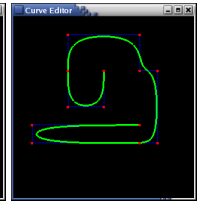
BSpline Curve Control Points



Default BSpline



BSpline with Discontinuity



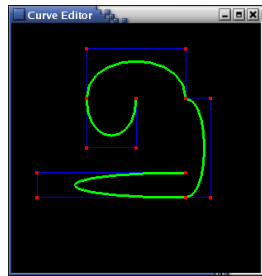
BSpline which passes through end points

Repeat interior control point

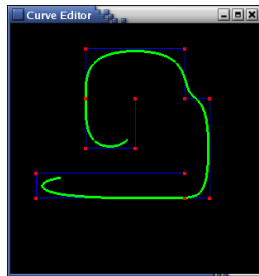
Repeat end points

MIT EECS 6.837, Durand and Cutler

Bézier is not the same as BSpline



Bézier

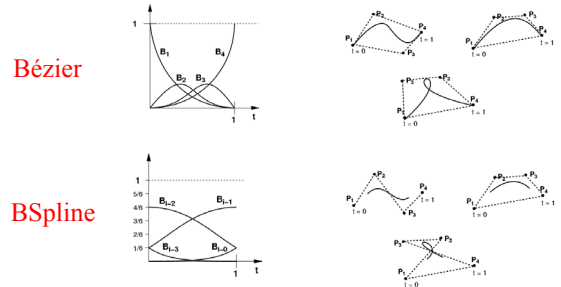


BSpline

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Bézier is not the same as BSpline

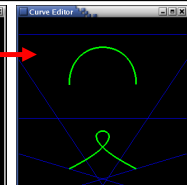
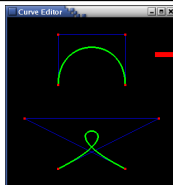
- Relationship to the control points is different



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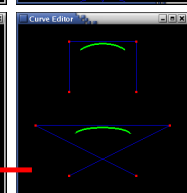
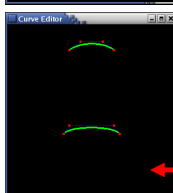
Converting between Bézier & BSpline

original control points as Bézier



new BSpline control points to match Bézier

new Bézier control points to match BSpline



original control points as BSpline

Converting between Bézier & BSpline

- Using the basis functions:

$$B_{\text{Bezier}} = \begin{pmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 3 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

$$B_{\text{B-Spline}} = \frac{1}{6} \begin{pmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 0 & 4 \\ -3 & 3 & 3 & 1 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

$$Q(t) = \mathbf{G} \mathbf{B} \mathbf{T}(t) = \text{Geometry } \mathbf{G} \cdot \text{Spline Basis } \mathbf{B} \cdot \text{Power Basis } \mathbf{T}(t)$$

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NURBS (generalized BSplines)

- BSpline: uniform cubic BSpline
- NURBS: Non-Uniform Rational BSpline
 - non-uniform = different spacing between the blending functions, a.k.a. knots
 - rational = ratio of polynomials (instead of cubic)

MIT EECS 6.837, Durand and Cutler

Questions?

MIT EECS 6.837, Durand and Cutler

Today

- Motivation
- Spline Curves
- Spline Surfaces / Patches
 - Tensor Product
 - Bilinear Patches
 - Bezier Patches
- Subdivision Surfaces

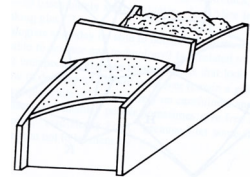
MIT EECS 6.837, Durand and Cutler

Tensor Product

- Of two vectors:

$$[a_1 \ a_2 \ a_3] \otimes [b_1 \ b_2 \ b_3 \ b_4] = \begin{bmatrix} a_1 b_1 & a_2 b_1 & a_3 b_1 \\ a_1 b_2 & a_2 b_2 & a_3 b_2 \\ a_1 b_3 & a_2 b_3 & a_3 b_3 \\ a_1 b_4 & a_2 b_4 & a_3 b_4 \end{bmatrix}$$

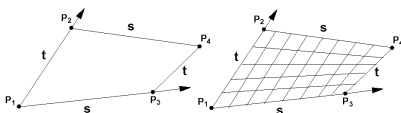
- Similarly, we can define a surface as the tensor product of two curves....



Farin, Curves and Surfaces for Computer Aided Geometric Design

Bilinear Patch

Bi-lerp a (typically non-planar) quadrilateral



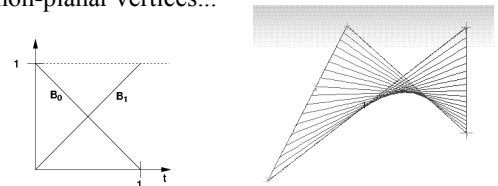
Notation: $\mathbf{L}(P_1, P_2, \alpha) \equiv (1 - \alpha)P_1 + \alpha P_2$

$$Q(s, t) = \mathbf{L}(\mathbf{L}(P_1, P_2, t), \mathbf{L}(P_3, P_4, t), s)$$

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Bilinear Patch

- Smooth version of quadrilateral with non-planar vertices...



- But will this help us model smooth surfaces?
- Do we have control of the derivative at the edges?

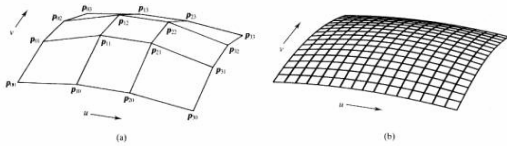
MIT EECS 6.837, Durand and Cutler

Bicubic Bezier Patch

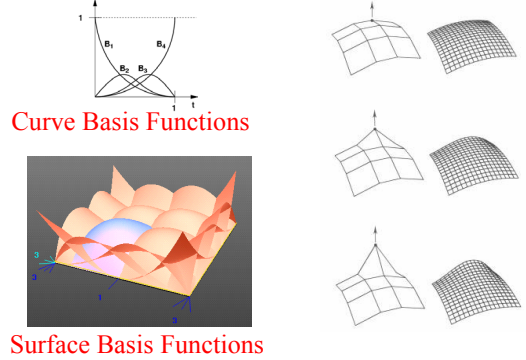
Notation: $CB(P_1, P_2, P_3, P_4, \alpha)$ is Bézier curve with control points P_i evaluated at α

Define "Tensor-product" Bézier surface

$$Q(s, t) = CB(CB(P_{00}, P_{01}, P_{02}, P_{03}, t), \\ CB(P_{10}, P_{11}, P_{12}, P_{13}, t), \\ CB(P_{20}, P_{21}, P_{22}, P_{23}, t), \\ CB(P_{30}, P_{31}, P_{32}, P_{33}, t), \\ s)$$

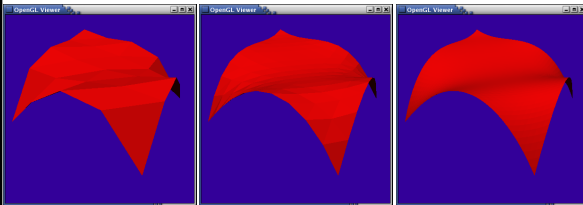


Editing Bicubic Bezier Patches



Bicubic Bezier Patch Tessellation

- Assignment 8: Given 16 control points and a tessellation resolution, create a triangle mesh



resolution:
5x5 vertices

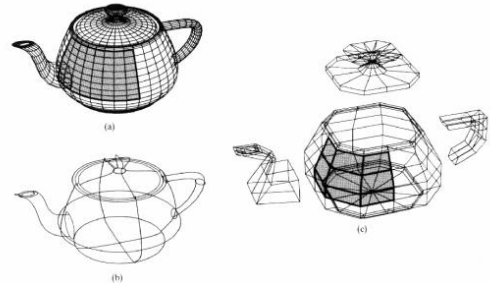
resolution:
11x11 vertices

resolution:
41x41 vertices

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Modeling with Bicubic Bezier Patches

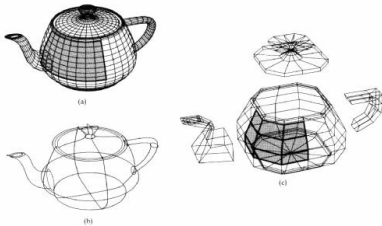
- Original Teapot specified with Bezier Patches



MIT EECS 6.837, Durand and Cutler

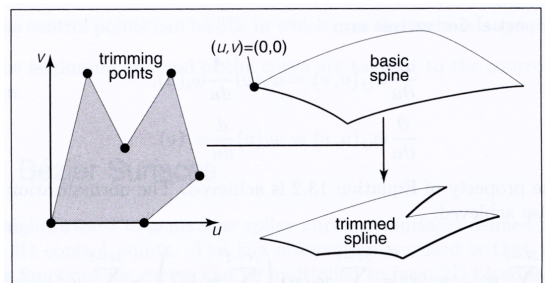
Modeling Headaches

- Original Teapot model is not "watertight":
intersecting surfaces at spout & handle, no bottom, a hole at the spout tip, a gap between lid & base



MIT EECS 6.837, Durand and Cutler

Trimming Curves for Patches



Shirley, Fundamentals of Computer Graphics

Questions?

- Bezier Patches?

or

- Triangle Mesh?



Henrik Wann Jensen

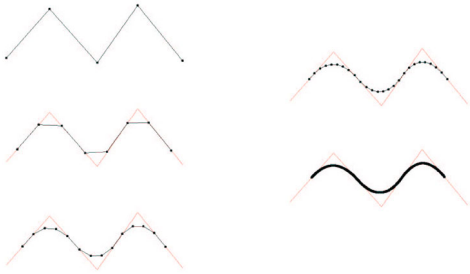
MIT EECS 6.837, Durand and Cutler

Today

- Review
- Motivation
- Spline Curves
- Spline Surfaces / Patches
- **Subdivision Surfaces**

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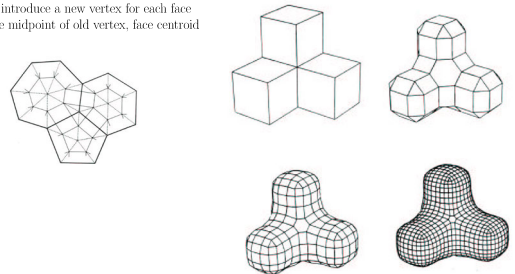
Chaikin's Algorithm



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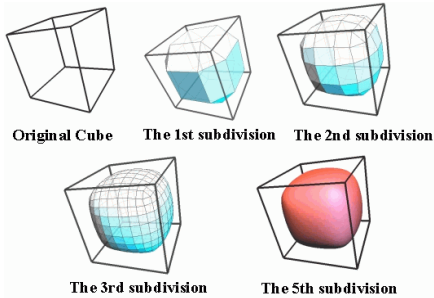
Doo-Sabin Subdivision

Idea: introduce a new vertex for each face
At the midpoint of old vertex, face centroid



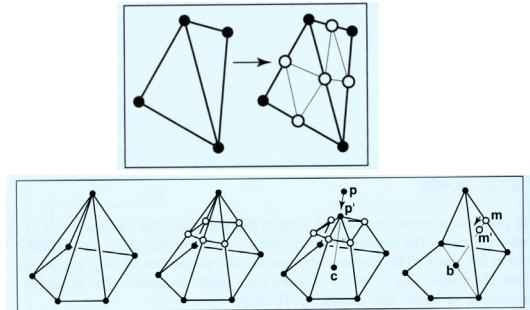
MIT EECS 6.837, Durand and Cutler

Doo-Sabin Subdivision



<http://www.ke.ics.saitama-u.ac.jp/xuz/pic/doo-sabin.gif>

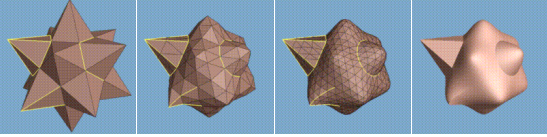
Loop Subdivision



Shirley, Fundamentals of Computer Graphics

Loop Subdivision

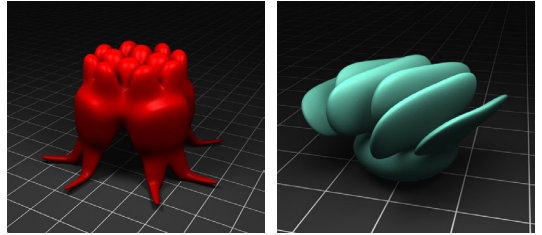
- Some edges can be specified as crease edges



<http://grail.cs.washington.edu/projects/subdivision/>

MIT EECS 6.837, Durand and Cutler

Questions?

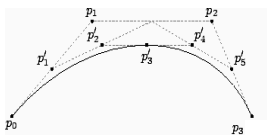


Justin Legakis

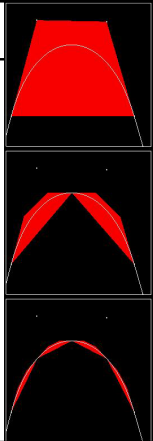
MIT EECS 6.837, Durand and Cutler

Neat Bézier Spline Trick

- A Bézier curve with 4 control points:
 - P_0 P_1 P_2 P_3
- Can be split into 2 new Bézier curves:
 - P_0 P'_1 P'_2 P'_3
 - P'_3 P'_4 P'_5 P_3



A Bézier curve is bounded by the convex hull of its control points.



MIT EECS 6.837, Durand and Cutler

Next Tuesday: (no class Thursday!)

Animation I:
Particle Systems

MIT EECS 6.837, Durand and Cutler