Sampling, Aliasing, & Mipmaps

Last Time?

• Global illumination "physically accurate light transport"



- The rendering equation $L(x',\omega') = E(x',\omega') + \int \rho_{x'}(\omega,\omega')L(x,\omega)G(x,x')V(x,x') dA$
- · The discrete radiosity equation

$$B_i = E_i + \rho_i \sum_{j=l} F_{ij} B_j$$

Diffuse reflection onlyView independent

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Last Time?

- Form factors
 - F_{ij} = fraction of light energy leaving patch j that arrives at patch i
 - Hemicube algorithm
- Advanced techniques
 - Progressive radiosity
 - Adaptive subdivision
 - Discontinuity meshing
 - Hierarchical radiosity



Today

- What is a Pixel?
- Examples of aliasing
- Sampling & Reconstruction
- Filters in Computer Graphics
- Anti-Aliasing for Texture Maps

What is a Pixel?

- My research during for my PhD was on sampling & aliasing with point-sampled surfaces, i.e., 3D objects
- This lecture is about sampling images



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More on Samples

- Most things in the real world are *continuous*, yet everything in a computer is *discrete*
- The process of mapping a continuous function to a discrete one is called *sampling*
- The process of mapping a continuous variable to a discrete one is called *quantization*
- To represent or render an image using a computer, we must both sample and quantize



An Image is a 2D Function

- An ideal image is a continuous function I(x,y) of intensities.
- It can be plotted as a height field.
- In general an image cannot be represented as a continuous, analytic function.
- Instead we represent images as tabulated functions.
- How do we fill this table?



Sampling Grid • We can generate the table values by multiplying the continuous image function by a sampling grid of Kronecker delta functions. The definiton of the 2-D Kronecker term definiton of the 2-D Kronecker $(x, y) = \begin{cases} 1, & (x, y) = (0, 0) \\ 0, & \text{otherwise} \end{cases}$ And a 2-D sampling grid: $\sum_{j=0}^{k-1} \sum_{j=0}^{n-1} \delta(u-i, v-j)$ MIT EECS 6.837



Questions?		
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Today

- What is a Pixel?
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Today

- What is a Pixel?
- Examples of Aliasing
- Sampling & Reconstruction – Sampling Density
 - Fourier Analysis & Convolution
- Filters in Computer Graphics
- Anti-Aliasing for Texture Maps

Sampling Density

- How densely must we sample an image in order to capture its essence?
- If we under-sample the signal, we won't be able to accurately reconstruct it...



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Sampling Density

• If we insufficiently sample the signal, it may be mistaken for something simpler during reconstruction (that's aliasing!)









Remember Fourier Analysis?

• We can transform from one domain to the other using the Fourier Transform.

Fourier
Transform
$$F(u, v) = \int_{-\infty-\infty}^{\infty} \int_{-\infty-\infty}^{\infty} f(x, y) e^{-i2\pi(ux+vy)} dxdy$$

Inverse
Fourier
Transform $f(x, y) = \int_{-\infty-\infty}^{\infty} F(u, v) e^{-i2\pi(ux+vy)} dudv$
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Remember Convolution?

- Some operations that are difficult to compute in the spatial domain can be simplified by transforming to its dual representation in the frequency domain.
- For example, convolution in the spatial domain is the same as multiplication in the frequency domain.

$$f(x) * h(x) \to F(u)H(u)$$

• And, convolution in the frequency domain is the same as multiplication in the spatial domain

$$F(u) * H(u) \to f(x)h(x)$$













Filters Weighting function or a convolution kernel Area of influence often bigger than "pixel" Sum of weights = 1 Each sample contributes the same total to image Constant brightness as object moves across the screen. No negative weights/colors (optional)

Filters

- Filters are used to
 - reconstruct a continuous signal from a sampled signal (reconstruction filters)
 - band-limit continuous signals to avoid aliasing during sampling (low-pass filters)
- Desired frequency domain properties are the same for both types of filters
- Often, the same filters are used as reconstruction and low-pass filters

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Post-Filtering

- Filter samples
- Compute the weighted average of many samples
- Regular or jittered sampling (better)



















Today • What is a Pixel? • Examples of Aliasing • Sampling & Reconstruction • Filters in Computer Graphics • Anti-Aliasing for Texture Maps - Magnification & Minification - Mipmaps - Anisotropic Mipmaps



Sampling Texture Maps

• When texture mapping it is rare that the screen-space sampling density matches the sampling density of the texture.



Original Texture



Magnification for Display for which we must use a reconstruction filter

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Linear Interpolation

- Tell OpenGL to use a tent filter instead of a box filter.
- Magnification looks better, but blurry

 (texture is under-sampled for this resolution)





Spatial Filtering

- Remove the high frequencies which cause artifacts in texture minification.
- Compute a spatial integration over the extent of the pixel
- This is equivalent to convolving the texture with a filter kernel centered at the sample (i.e., pixel center)!

Expensive to do during

rasterization, but an

approximation it can be precomputed



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Storing MIP Maps

- Can be stored compactly
- Illustrates the 1/3 overhead of maintaining the MIP map





10-level mip map

Memory format of a mip map









