## The Graphics Pipeline: Projective Transformations

## Last Week:

- Animation \& Quaternions
- Finite Element Simulations
- collisions, fracture, \& deformation



## Schedule

- Final Project
- Post your ideas on the web page
- Meet with staff to talk about project ideas - sign up for an appointment on Friday
- Proposal due on Monday October $27^{\text {th }}$
- Friday October $24^{\text {th }}$ : Assignment 5 due
- Office Hours this week:
- Tuesday after class (Rob - student center)
- Wednesday 7-9 (Patrick - student center)
- Thursday after class (Fredo - student center)
- Friday 3-5, student center (Barb - student center)

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## Questions?

## Today

- Review \& Schedule
- Ray Casting / Tracing vs. Scan Conversion
- The Graphics Pipeline
- Projective Transformations


## What have we done so far?

- Ray Casting / Tracing
- ray/primitive intersections
- transformations
- local shading (diffuse, ambient, $\rightarrow$ BRDFs)
- global effects (shadows, transparency, caustics, ... )


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## Ray Casting / Tracing

- Advantages?
- Smooth variation of normal, silhouettes
- Generality: can render anything that can be intersected with a ray
- Atomic operation, allows recursion
- Disadvantages?
- Time complexity (N objects, R pixels)
- Usually too slow for interactive applications
- Hard to implement in hardware (lacks computation coherence, must fit entire scene in memory)


## How do we render interactively?

- Use the graphics hardware (the graphics pipeline), via OpenGL, MesaGL, or DirectX
- Most global effects available in ray tracing will be sacrificed, but some can be approximated.



## Scan Conversion - Graphics Pipeline

- Primitives are processed one at a time
- Early stages involve analytic processing
- Sampling occurs late in the pipeline
- Minimal state required
glBegin (GL_TRIANGLES) glNormal3f(...)
glVertex3f(...) glVertex3f(...) glVertex3f(...) glEnd();


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```
for every object in the scene
```

    shade the vertices
    scan convert the object to the framebuffer
    interpolate the color computed for each vertex
    remember the closest value per pixel
    glBegin (GL_TRIANGLES)
glNormal3f(...)
glVertex3f(...)
glVertex3f(...)
glVertex3f(...)
glEnd();


## Limitations of Scan Conversion

- Restricted to scan-convertible primitives
- Object polygonization
- Faceting, shading artifacts
- Effective resolution is hardware dependent
- No handling of shadows, reflection, transparency
- Problem of overdraw (high depth complexity)

- What if there are more triangles than pixels?


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## The Graphics Pipeline

| Modeling Transformations | Input: <br> Geometric model: <br> Description of all object, surface, and <br> light source geometry and transformations <br> Lighting model: <br> Computational description of object and <br> light properties, interaction (reflection) <br> Synthetic Viewpoint (or Camera): <br> Eye position and viewing frustum <br> Raster Viewport: <br> Pixel grid onto which image plane is mapped <br> Output: <br> Colors/Intensities suitable for framebuffer display (For example, 24 -bit RGB value at each pixel) <br> MIT EECS 6.837, Durand and Cutler |
| :---: | :---: |
| $\begin{gathered} \text { Illumination } \\ \text { (Shading) } \\ \hline \end{gathered}$ |  |
| Viewing Transformation <br> (Perspective / Orthographic) |  |
| Clipping |  |
| $\begin{gathered} \text { Projection } \\ \text { (to Screen Space) } \end{gathered}$ |  |
| Scan Conversion (Rasterization) |  |
| Visibility / Display |  |
|  |  |

## The Graphics Pipeline

$\left.\begin{array}{|c|c|}\hline \begin{array}{c}\text { Modeling } \\ \text { Transformations }\end{array} & \text { - Primitives are processed in a series } \\ \text { of stages }\end{array}\right]$

## Modeling Transformations

| Modeling <br> Transformations | - 3D models defined in their own coordinate system (object space) |
| :---: | :---: |
| Illumination (Shading) | - Modeling transforms orient the |
| Viewing Transformation (Perspective / Orthographic) | models within a common |
| Clipping | ate frame (world space) |
| $\begin{gathered} \text { Projection } \\ \text { (to Screen Space) } \end{gathered}$ |  |
| Scan Conversion (Rasterization) |  |
| Visibility / Display |  |
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Illumination (Shading) (Lighting)

| Modeling Transformations | - Vertices lit (shaded) according to material properties, surface properties (normal) and light sources <br> - Local lighting model (Diffuse, Ambient, Phong, etc.) |
| :---: | :---: |
| Illumination (Shading) |  |
| Viewing Transformation (Perspective / Orthographic) |  |
| Clipping |  |
| Projection (to Screen Space) |  |
| Scan Conversion (Rasterization) | $\square+\frac{0}{4}+$ |
| Visibility / Display |  |
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## Clipping



## Projection



| Visibility / Display |  |
| :---: | :---: |
| $\underset{\substack{\text { Madeding } \\ \text { Trasternions }}}{\text { a }}$ | - Each pixel remembers the closest object (depth buffer) |
|  |  |
| $\begin{array}{\|c\|} \hline \text { Viewing Transformation } \\ \text { (Perspective / Orthographic) } \\ \hline \end{array}$ |  |
| Clipping | - Almost every step in the graphics pipeline involves a change of coordinate system. Transformations are central to understanding 3D computer graphics. |
|  |  |
| $\substack{\text { Scan Comevesion } \\ \text { RRaseraxion) }}$ |  |
| biliy Disphy |  |



## Scan Conversion (Rasterization)

| Modeling <br> Transformations |
| :---: |
| Illumination <br> (Shading) |
| Viewing Transformation |

- Rasterizes objects into pixels
- Interpolate values as we go (color, depth, etc.)


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## Common Coordinate Systems

- Object space
- local to each object
- World space
- common to all objects
- Eye space / Camera space - derived from view frustum
- Clip space / Normalized Device Coordinates (NDC)
$-[-1,-1,-1] \rightarrow[1,1,1]$
- Screen space
- indexed according to hardware attributes



## Questions?

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- Projective Transformations
- Transformations \& Homogeneous Coordinates
- Orthographic \& Perspective Projections
- Canonical View Volume


## Homogeneous Coordinates

- Most of the time $w=1$, and we can ignore it

$$
\left(\begin{array}{c}
x^{\prime} \\
y^{\prime} \\
z^{\prime} \\
1
\end{array}\right)=\left(\begin{array}{llll}
a & b & c & d \\
e & f & g & h \\
i & j & k & l \\
0 & 0 & 0 & 1
\end{array}\right)\left(\begin{array}{l}
x \\
y \\
z \\
1
\end{array}\right)
$$

- If we multiply a homogeneous coordinate by an affine matrix, w is unchanged


## Orthographic vs. Perspective

- Orthographic

- Perspective



## Remember Transformations?



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## Homogeneous Visualization

- Divide by w to normalize (homogenize)
- $\mathrm{W}=0$ ? Point at infinity (direction)
$(0,0,1)=(0,0,2)=$.
$(7,1,1)=(14,2,2)=$
$(4,5,1)=(8,10,2)=$.


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## Simple Orthographic Projection

- Project all points along the $z$ axis to the $z=0$ plane


$$
\left(\begin{array}{l}
x \\
y \\
0 \\
1
\end{array}\right)=\left(\begin{array}{llll}
1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 1
\end{array}\right)\left(\begin{array}{l}
x \\
y \\
z \\
1
\end{array}\right)
$$

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## Simple Perspective Projection

- Project all points along the $z$ axis to the $z=d$ plane, eyepoint at the origin:



## What if the $p_{z}$ is $\leq$ eye $_{z}$ ?




## Where are projections in the pipeline?



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## World Space $\rightarrow$ Eye Space

Positioning the camera


Translation + Change of orthonormal basis (Lecture 4)

- Given: coordinate frames xyz \& uvn, and point $\mathbf{p}=(x, y, z)$
- Find: $\mathbf{p}=(u, v, n)$



## Change of Orthonormal Basis

$$
\left(\begin{array}{l}
u \\
v \\
n
\end{array}\right)=\left(\begin{array}{lll}
u_{x} & u_{y} & u_{z} \\
v_{x} & v_{y} & v_{z} \\
n_{x} & n_{y} & n_{z}
\end{array}\right)\left(\begin{array}{l}
x \\
y \\
z
\end{array}\right)
$$


where:
$u_{x}=\mathbf{x} . \mathbf{u}$
$u_{y}=\mathbf{y} . \mathbf{u}$
etc.

## Normalized Device Coordinates

- Clipping is more efficient in a rectangular, axis-aligned volume: $(-1,-1,-1) \rightarrow(1,1,1) \quad$ OR $\quad(0,0,0) \rightarrow(1,1,1)$



## Canonical Orthographic Projection

Normalized Device Coordinates


Orthographic

$$
\left[\begin{array}{c}
x^{\prime} \\
y^{\prime} \\
z^{\prime} \\
1
\end{array}\right]=\left[\begin{array}{cccc}
\frac{2}{\text { right - left }} & 0 & 0 & \frac{-(\text { right }+ \text { left })}{\text { right }- \text { left }} \\
0 & \frac{2}{\text { bottom - top }} & 0 & \frac{-(\text { bottom }+ \text { top) }}{\text { bottom }- \text { top }} \\
0 & 0 & \frac{2}{\text { far - near }} & \frac{-(\text { far }+ \text { near })}{\text { far - near }} \\
0 & 0 & 0 & 1
\end{array}\right]\left[\begin{array}{l}
x \\
y \\
z \\
1
\end{array}\right]
$$

## Canonical Perspective Projection



Perspective

$$
\left[\begin{array}{c}
x^{\prime} w \\
y^{\prime} w \\
z^{\prime} w \\
w
\end{array}\right]=\left[\begin{array}{cccc}
\frac{2 \cdot \text { near }}{\text { right }- \text { left }} & 0 & \frac{-(\text { right }+ \text { left })}{\text { right }- \text { left }} & 0 \\
0 & \frac{2 \cdot \text { near }}{\text { bottom }- \text { top }} & \frac{- \text { (bottom }+ \text { top })}{\text { bottom }- \text { top }} & 0 \\
0 & 0 & \frac{\text { far }+ \text { near }}{\text { far - near }} & \frac{-2 \cdot \text { near } \cdot \text { far }}{\text { far }- \text { near }} \\
0 & 0 & 1 & 0
\end{array}\right]\left[\begin{array}{c}
x \\
y \\
z \\
1 \\
0
\end{array}\right]
$$



