

## Ray Casting



MIT EECS 6.837  
Frédo Durand and Barb Cutler  
Some slides courtesy of Leonard McMillan

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## Luxo Jr

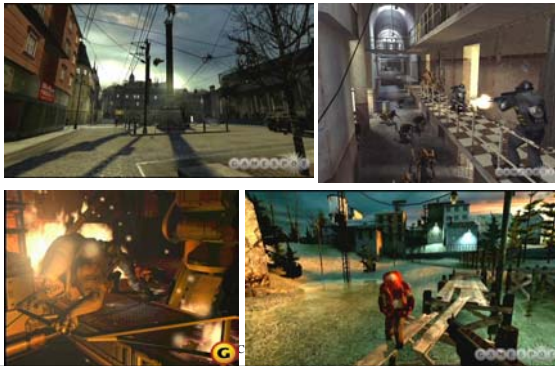
- Pixar Animation Studios, 1986
- Director: John Lasseter



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## Games



## Image-based Rendering

- Use images as inputs and representation
- E.g. Image-based modeling and photo editing  
Boh, Chen, Dorsey and Durand 2001



Input image



New viewpoint



Relighting

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## Administrative

- Assignment 1
  - Due Wednesday September 17

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## Calendar

- **1st quiz – Tuesday October 07th**
- **2nd quiz – Thursday Nov 20th**
- **Week Dec 1-5 project presentation**
- **Last day of class: December 9: best projects & final report due**

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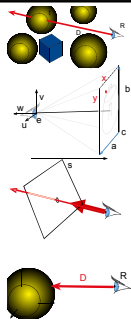
## Questions?

## Overview of the semester

- Ray Tracing
  - Quiz 1
- Animation, modeling, IBMR
  - Choice of final project
- Rendering pipeline
  - Quiz 2
- Advanced topics

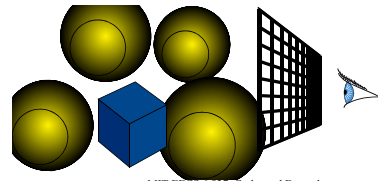
## Overview of today

- Introduction
- Camera and ray generation
- Ray-plane intersection
- Ray-sphere intersection



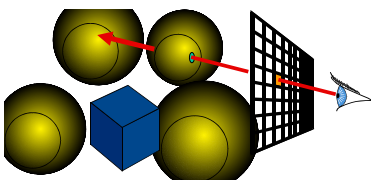
## Ray Casting

For every pixel  
Construct a ray from the eye  
For every object in the scene  
Find intersection with the ray  
Keep if closest



## Ray Casting

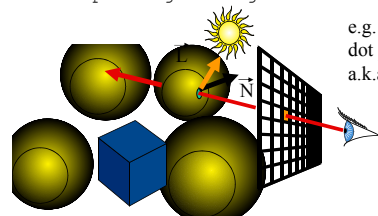
For every pixel  
Construct a ray from the eye  
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## Shading

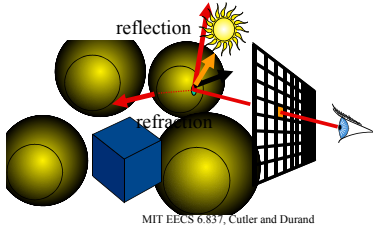
For every pixel  
Construct a ray from the eye  
For every object in the scene  
Find intersection with the ray  
Keep if closest  
Shade depending on light and normal vector

e.g. diffuse shading:  
dot product  $\vec{N} \cdot \vec{L}$   
a.k.a. Lambertian



## Ray Tracing

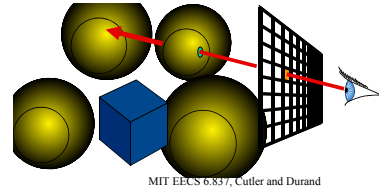
- Secondary rays (shadows, reflection, refraction)
- In a couple of weeks



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## Ray representation?

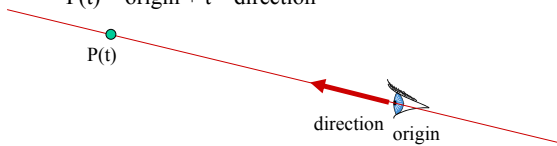


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## Ray representation

- Two vectors:
  - Origin
  - Direction (normalized is better)
- Parametric line
  - $P(t) = \text{origin} + t * \text{direction}$

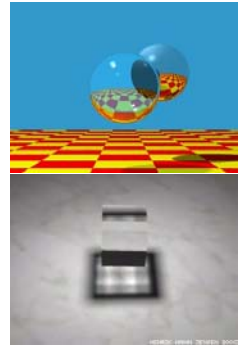


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## Ray Tracing

- Original Ray-traced image by Whitted
- Image computed using the Dali ray tracer by Henrik Wann Jensen
- Environment map by Paul Debevec



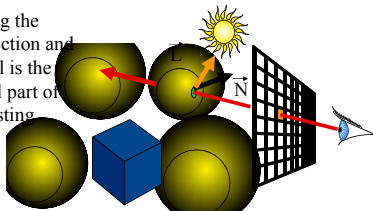
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## Ray casting

- For every pixel  
Construct a ray from the eye  
For every object in the scene  
**Find intersection with the ray**  
Keep if closest  
Shade depending on light and **normal** vector

Finding the intersection and normal is the central part of ray casting

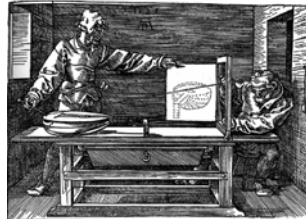


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## Durer's Ray casting machine

- Albrecht Durer, 16<sup>th</sup> century



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## Durer's Ray casting machine

- Albrecht Durer, 16<sup>th</sup> century



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## Durer's Ray casting machine

- Albrecht Durer, 16<sup>th</sup> century



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## Questions?

- Image computed using the Dali ray tracer from Henrik Wann Jensen
- Model Stephen Duck

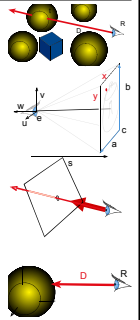


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## Overview of today

- Introduction
- Camera and ray generation
- Ray-plane intersection
- Ray-sphere intersection

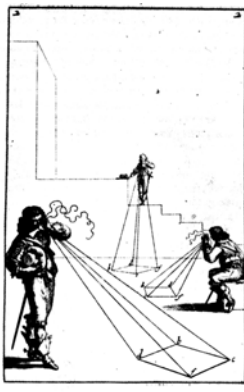


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## Cameras

- For every pixel
- Construct a ray from the eye
- For every object in the scene
- Find intersection with the ray
  - Keep if closest

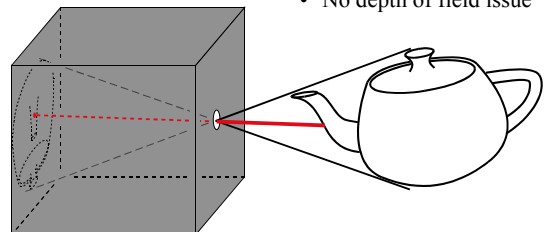


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## Pinhole camera

- Box with a tiny hole
- Inverted image
- Similar triangles
- Perfect image if hole infinitely small
- Pure geometric optics
- No depth of field issue



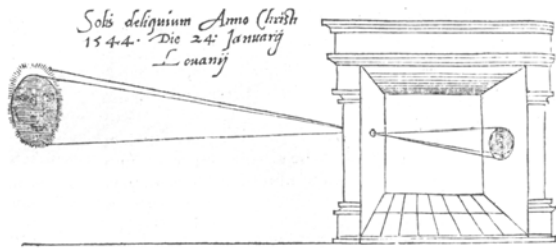
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## Oldest illustration

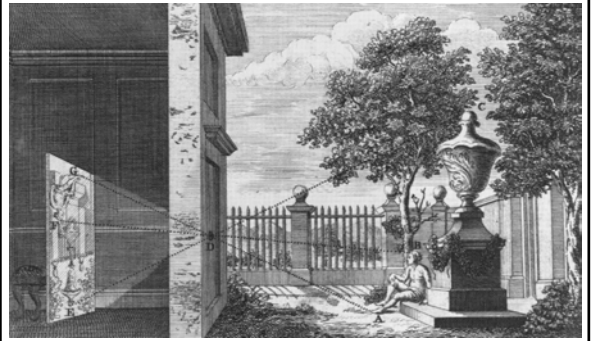
- From R. Gemma Frisius, 1545



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## Camera Obscura



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## Abelardo Morell

- Photographer who turns hotel room into a camera obscura (pinhole optics)

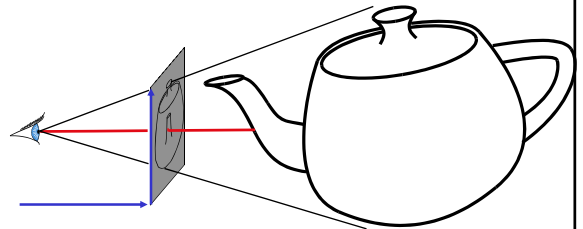


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## Simplified pinhole camera

- Eye-image pyramid (frustum)
- Note that the distance/size of image are arbitrary



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## Durer's Ray casting machine

- Albrecht Durer, 16<sup>th</sup> century

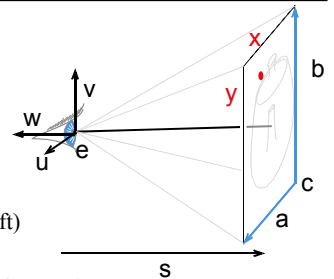


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## Camera description

- Eye point  $e$
- Orthobasis  $u, v, w$
- Image distance  $s$
- Image rectangle  $(u_0, v_0, u_1, v_1)$



- Deduce  $c$  (lower left)
- Deduce  $a$  and  $b$
- Screen coordinates in  $[0,1] \times [0,1]$
- A point is then  $c + x a + y b$

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## Alternative perspective encoding

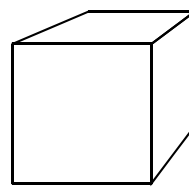
- 4x4 matrix & viewing frustum
- More about that next week

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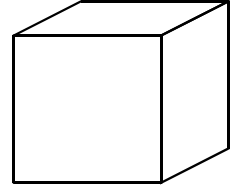
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## Orthographic camera

- Parallel projection
- No foreshortening
- No vanishing point



perspective

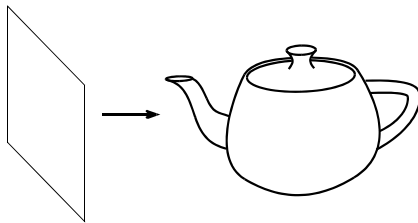


orthographic

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## Orthographic camera description

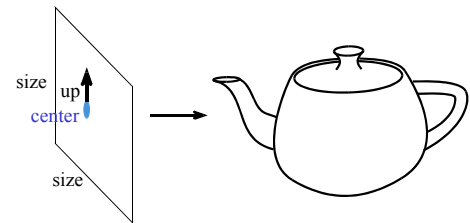


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## Orthographic camera description

- Direction
- Image size
- Image center
- Up vector

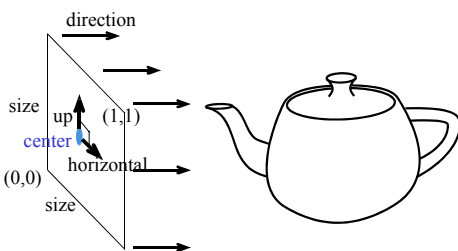


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## Orthographic ray generation

- Direction is constant
- Origin = center + (x-0.5)\*size\*up + (y-0.5)\*size\*horizontal



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## Other weird cameras

- E.g. fish eye, omnimax, panorama



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## Questions?

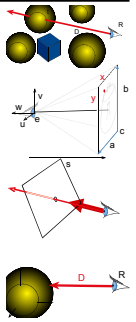


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## Overview of today

- Introduction
- Camera and ray generation
- **Ray-plane intersection**
- Ray-sphere intersection



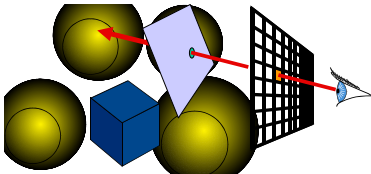
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## Ray Casting

For every pixel  
 Construct a ray from the eye  
 For every object in the scene  
**Find intersection with the ray**  
 Keep if closest

First we will study ray-plane intersection

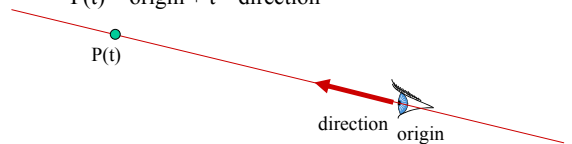


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## Recall: Ray representation

- Two vectors:
  - Origin
  - Direction (normalized)
- Parametric line
  - $P(t) = \text{origin} + t * \text{direction}$

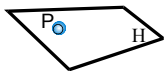


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## 3D plane equation

- Implicit plane equation  
 $H(p) = Ax + By + Cz + D = 0$
- Gradient of  $H$ ?

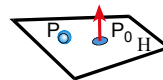


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## 3D plane equation

- Implicit plane equation  
 $H(p) = Ax + By + Cz + D = 0$
- Gradient of  $H$ ?
- Plane defined by
  - $P_0(x, y, z, 1)$
  - $n(A, B, C, 1)$



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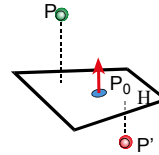
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## Explicit vs. implicit?

- Plane equation is implicit
  - Solution of an equation
  - Does not tell us how to generate a point on the plane
  - Tells us how to check that a point is on the plane
- Ray equation is explicit
  - Parametric
  - How to generate points
  - Harder to verify that a point is on the ray

## Plane-point distance

- Plane  $H_p=0$
- If  $n$  is normalized  
 $d=HP$
- Signed distance!

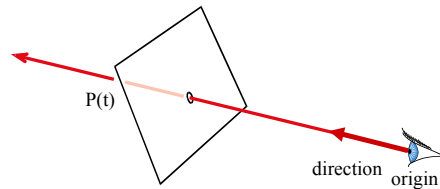


## Explicit vs. implicit?

- Plane equation is implicit
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  - Tells us how to check that a point is on the plane
- Ray equation is explicit
  - Parametric
  - How to generate points
  - Harder to verify that a point is on the ray
- Exercise: explicit plane and implicit ray

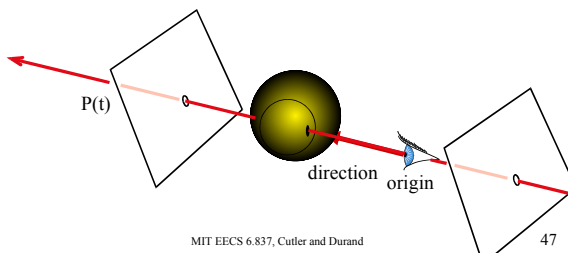
## Line-plane intersection

- Insert explicit equation of line into implicit equation of plane



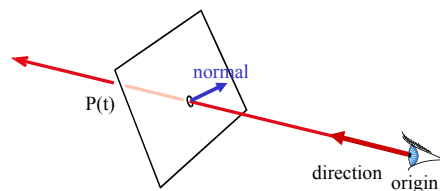
## Additional house keeping

- Verify that intersection is closer than previous
- Verify that it is in the allowed range (in particular not behind the camera,  $t < 0$ )



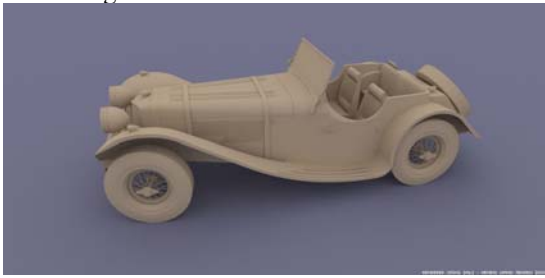
## Normal

- For shading (recall, diffuse: dot product between light and normal)
- Simply the normal to the plane



## Questions?

- Image by Henrik Wann Jensen using Ray Casting

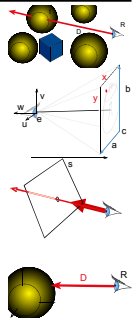


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## Overview of today

- Introduction
- Camera and ray generation
- Ray-plane intersection
- Ray-sphere intersection

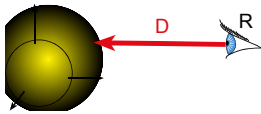


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## Sphere equation

- Sphere equation (implicit):  $\|P\|^2 = r^2$
- (assume centered at origin, easy to translate)

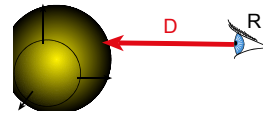


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## Ray-Sphere Intersection

- Sphere equation (implicit):  $\|P\|^2 = r^2$
- Ray equation (explicit):  $P(t) = R + tD$  with  $\|D\| = 1$
- Intersection means both are satisfied

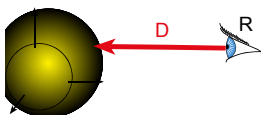


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## Ray-Sphere Intersection

$$\begin{aligned}
 0 &= P \cdot P - r^2 \\
 &= (\mathbf{R} + t\mathbf{D}) \cdot (\mathbf{R} + t\mathbf{D}) - r^2 \\
 &= \mathbf{R} \cdot \mathbf{R} + 2t\mathbf{D} \cdot \mathbf{R} + t^2\mathbf{D}^2 - r^2 \\
 &= t^2 + 2t\mathbf{D} \cdot \mathbf{R} + \mathbf{R} \cdot \mathbf{R} - r^2
 \end{aligned}$$



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## Ray-Sphere Intersection

- This is just a quadratic  $at^2 + bt + c = 0$ , where
  - $a = 1$
  - $b = 2\mathbf{D} \cdot \mathbf{R}$
  - $c = \mathbf{R} \cdot \mathbf{R} - r^2$
- With discriminant

$$d = \sqrt{b^2 - 4ac}$$

- and solutions

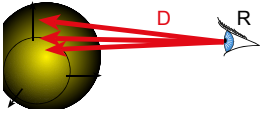
$$t_{\pm} = \frac{-b \pm d}{2a}$$

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## Ray-Sphere Intersection

- Discriminant  $d = \sqrt{b^2 - 4ac}$
- Solutions  $t_{\pm} = \frac{-b \pm d}{2a}$
- Three cases, depending on sign of  $b^2 - 4ac$
- Which root ( $t_+$  or  $t_-$ ) should you choose?
  - Closest positive! (usually  $t_-$ )

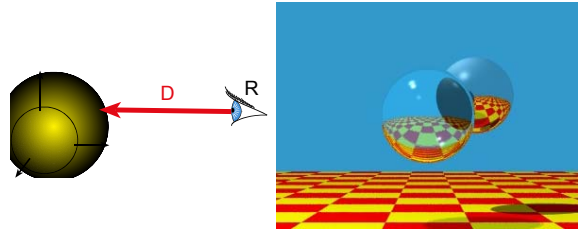


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## Ray-Sphere Intersection

- So easy that all ray-tracing images have spheres!

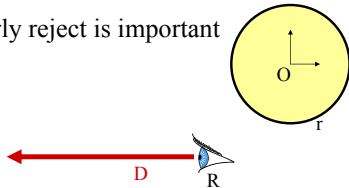


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## Geometric ray-sphere intersection

- Try to shortcut (easy reject)
- e.g.: if the ray is facing away from the sphere
- Geometric considerations can help
- In general, early reject is important

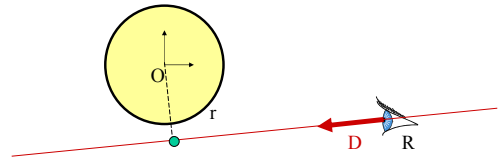


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## Geometric ray-sphere intersection

- What geometric information is important?
  - Inside/outside
  - Closest point
  - Direction

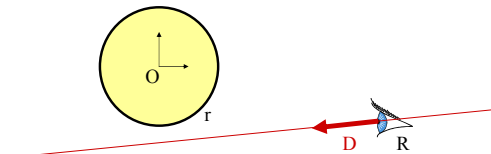


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## Geometric ray-sphere intersection

- Find if the ray's origin is outside the sphere
  - $R^2 > r^2$
  - If inside, it intersects
  - If on the sphere, it does not intersect (avoid degeneracy)

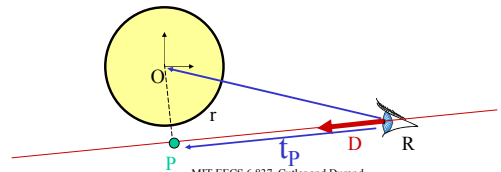


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## Geometric ray-sphere intersection

- Find if the ray's origin is outside the sphere
- Find the closest point to the sphere center
  - $t_p = RO \cdot D$
  - If  $t_p < 0$ , no hit



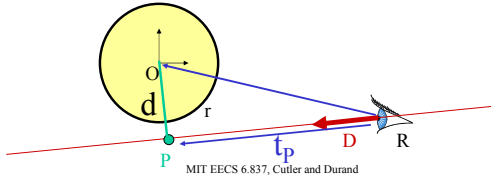
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## Geometric ray-sphere intersection

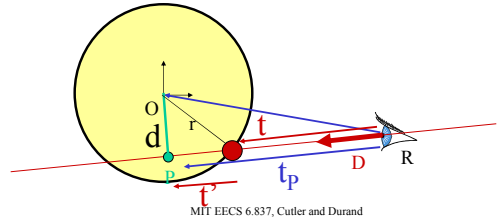
- Find if the ray's origin is outside the sphere
- Find the closest point to the sphere center
  - If  $t_p < 0$ , no hit
- Else find squared distance  $d^2$ 
  - Pythagoras:  $d^2 = R^2 - t_p^2$
  - ... if  $d^2 > r^2$  no hit



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## Geometric ray-sphere intersection

- Find if the ray's origin is outside the sphere
- Find the closest point to the sphere center
  - If  $t_p < 0$ , no hit
- Else find squared distance  $d^2$ 
  - if  $d^2 > r^2$  no hit
- If outside  $t = t_p - t'$ 
  - $t'^2 + d^2 = r^2$
- If inside  $t = t_p + t'$



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## Geometric vs. algebraic

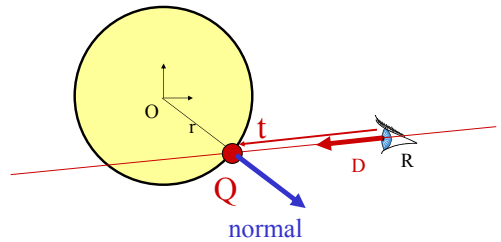
- Algebraic was more simple (and more generic)
- Geometric is more efficient
  - Timely tests
  - In particular for outside and pointing away

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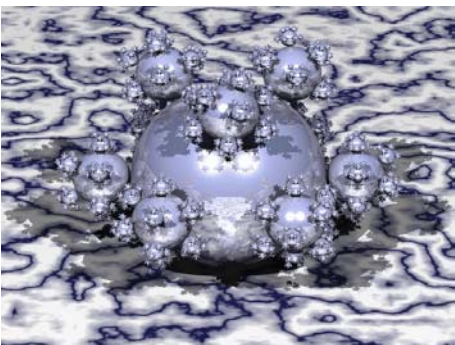
## Normal

- Simply  $Q/\|Q\|$



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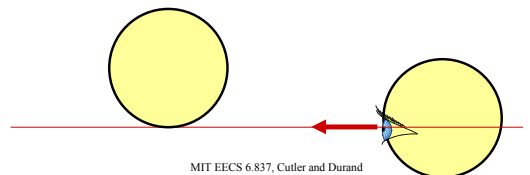
## Questions?



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## Precision

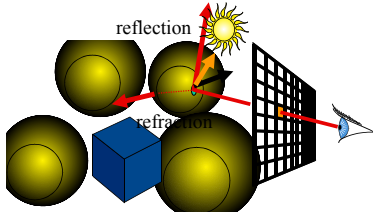
- What happens when
  - Origin is on an object?
  - Grazing rays?
- Problem with floating-point approximation



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## The evil $\epsilon$

- In ray tracing, do NOT report intersection for rays starting at the surface (no false positive)
  - Because secondary rays
  - Requires epsilons

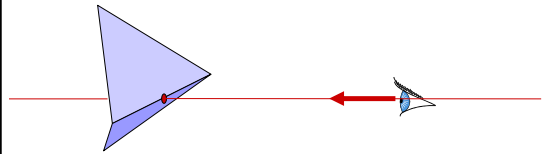


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## The evil $\epsilon$ : a hint of nightmare

- Edges in triangle meshes
  - Must report intersection (otherwise not watertight)
  - No false negative



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## Assignment 1

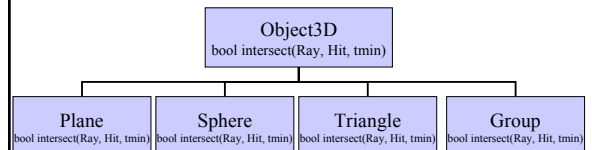
- Write a basic ray caster
  - Orthographic camera
  - Spheres
  - Display: constant color and distance
- We provide
  - Ray
  - Hit
  - Parsing
  - And linear algebra, image

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## Object-oriented design

- We want to be able to add primitives easily
  - Inheritance and virtual methods
- Even the scene is derived from Object3D!



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## Ray

```
//////////
class Ray {
//////////

    Ray () {}
    Ray (const Vec3f &dir, const Vec3f &orig)
    { _dir =dir; _orig=orig;}
    Ray (const Ray& r) { *this=r;}

    const Vec3f &origin() {return _orig;}
    const Vec3f &direction() {return &dir;}
    Vec3f pointAtParameter (float t) {return _orig+t*_dir;}

private:
    Vec3f _dir;
    Vec3f _orig;
};
```

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## Hit

- Store intersection point & various information

```
//////////
class Hit {
//////////

    float _t;
    Vec3f _color;
    //Material *_material;
    //Vec3f _normal;
};
```

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## Tasks

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- Abstract Object3D
- Sphere and intersection
- Scene class
- Abstract camera and derive Orthographic
- Main function

## Thursday: More Ray Casting

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- Other primitives
  - Boxes
  - Triangles
  - IFS?
- Antialiasing

